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ARE: A System for Automated Reverse Engineering

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Introduction

- Goal: Enable users or semi-automated planners to iteratively negate branches and fabricate paths to reach areas of interest, explore unvisited blocks, and test code units without the benefit of source code
- Applications: Program <u>analysis</u> (e.g., how are sockets used?), verification (e.g., are quality objectives still satisfied?), and optimization (e.g., are bounds exceeded?)
- **Note:** Analysts may further restrict the set



o Instrumentation, e.g., Pin ○ Emulation, e.g., TEMU

of acceptable <u>solutions</u>, e.g., "all but the last byte of an array must be in [0x20, 0x7E]"

○ First-party, e.g., COMET

Static Analysis: Representations

- **REIL:** Reverse Engineering Intermediate Language
 - ADD, SUB, MUL, DIV, MOD, BSH (binary shift) • Arithmetic:
 - **Bitwise**: AND, OR, XOR (can derive "NOT" from XOR)
 - Conditional: BISZ (Boolean is-zero), JCC (jump conditional)
 - Data transfer: LDM (load), STM (store), STR (store to register)
 - UNDEF (undefined), UNKN (unknown), NOP (no-op) • Other:
- **PREIL:** Power-REIL (more precise, faster, and clearer)
 - LSH (left shift) and RSH (right shift) instead of BSH • Arithmetic:
 - **Bitwise**: Same as REIL (but allows bit ranges, resizing, etc.)
 - Conditional: Adds IFM (conditional STM), IFR (conditional STR)
 - **Data transfer:** Same as REIL (but allows multiple memories, etc.)
 - Other: Same as REIL (but allows labels, macros, etc.)

Constraint Analysis: Inputs

- **Trace:** {(seq, ip, tid)}
 - Sequence number (optional; for reference to full, uncut trace) o seq:
 - Instruction pointer (raw bytes and disassembly is in full trace) • **ip**:
 - Thread identifier (pid and values read/written are in full trace) \circ tid:
- **Code:** {(ip, size, list)}
 - Machine's instruction size (for whether branches were taken) o size: List of PREIL instructions (for a single machine instruction) o list:
- **Patch:** {(seq, it, val)}
 - **it**: Target (i.e., "<register>_<tid>" or "<memory>[<address>]") Value assigned to **it** before **seq** (for partial observability) • **val**:
- **Others:** Input constraints, output constraints, and settings

Constraint Analysis: Queries



Constraint Analysis: Components

- **COMET:** Constraint Optimization, Management, Extensions, and Translations
 - Weakest preconditions for a given path • Constraint:
 - **Optimization:** Reduce complexity of the constraint program
 - **Management:** Services, e.g., for joining subproblems
 - Additional constraints, e.g., around interesting code Extensions: Ο
 - **Translations:** Various SMT solvers, e.g., STP and Boolector

• **Optimization:** Cutting out unnecessary constraints

- **SLICE:** Statically Limited Irrelevant Constraint Elimination
 - Example: Remove PREIL for unused flags during preprocessing
- **DICE:** Dynamic Irrelevant Constraint Elimination (path specific)
- **TMF:** Taint Modeling Function (for Input-Output Relationships)

TMF Options and Results

1. Temporary variable for each operation

Summary and Conclusions

• **Target:** Programs without source Initial state: A known execution path Subproblem Selection (Planner) approaches yet <u>avoids</u> a <u>dangerous</u> block • Static analysis: Helps determine that the Simplified Collapsed block is a relatively nearby area of interest **TMF** Formulas Taint Graphs • **Dynamic analysis:** Suggests <u>paths</u> through the area that <u>may be feasible</u> Constraint Solver Interface (CSI) • **Constraint analysis:** Provides inputs for feasible paths or <u>recognizes impossibilities</u> Reduced State Con-Trace and • **Benefit:** Directed search avoids straints Patches <u>reevaluation</u> of known paths and the high cost of tempting yet <u>futile</u> tracks $\mathsf{COMET} \leftrightarrow \mathsf{Solver}(\mathsf{SMT})$ • **Conclusion:** Combined analysis can Input Assignments (solutions) <u>effectively</u> handle binary code paths

Data Flow

PREIL

Instruc-

tions

• Advantage: State of the art DICE yet easy to read and understand

2. Single expression for each branch variable

- **Example:** $b1 = (!(!(0xfffffd0 + eax_1) 64 0x9))) \&$ $(!(((0xfffffd0 + eax_1) - 64 0x9)) & 0x100000000) >> 0x20)) = 0$
- Advantage: Maximal flexibility for constraint solvers' optimizers
- 3. Temporaries from common subexpression elimination
 - **Example:** $t1 = (0xfffffd0 + eax_1) -_{64} 0x9;$ b1 = (!(!t1)) & (!((t1 & 0x10000000) >> 0x20)) = 0
 - Advantage: Reduces execution time for solvers with weak optimizers
- **Result:** Order of magnitude size reduction for each problem

• Advantage: Enables each constraint problem to cover a longer path

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