

HAMR - High-Assurance Modeling and Rapid Engineering for Embedded Systems Using AADL

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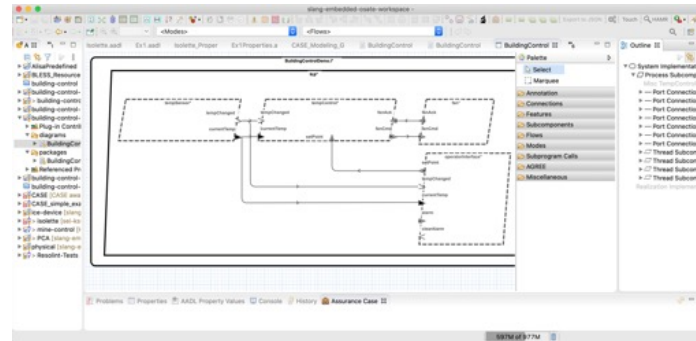
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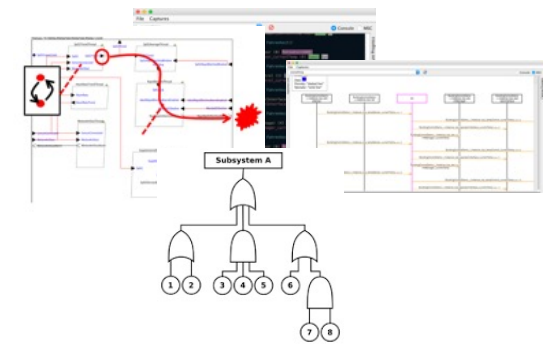
What is HAMR?

HAMR is a model-driven development tool-chain for high-assurance embedded systems

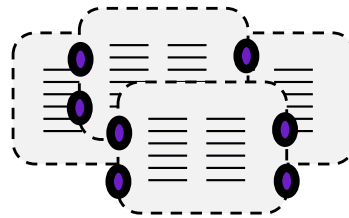
Modeling, analysis, and verification in the AADL modeling language



Leveraging analysis from AADL community



Component development and verification in multiple languages



- C
- Slang (safety-critical subset of Scala with a contract verification framework)
- CakeML (ML-variant with verified compiler)

Deployments aligned with AADL run-time on multiple platforms



DARPA CASE Approach

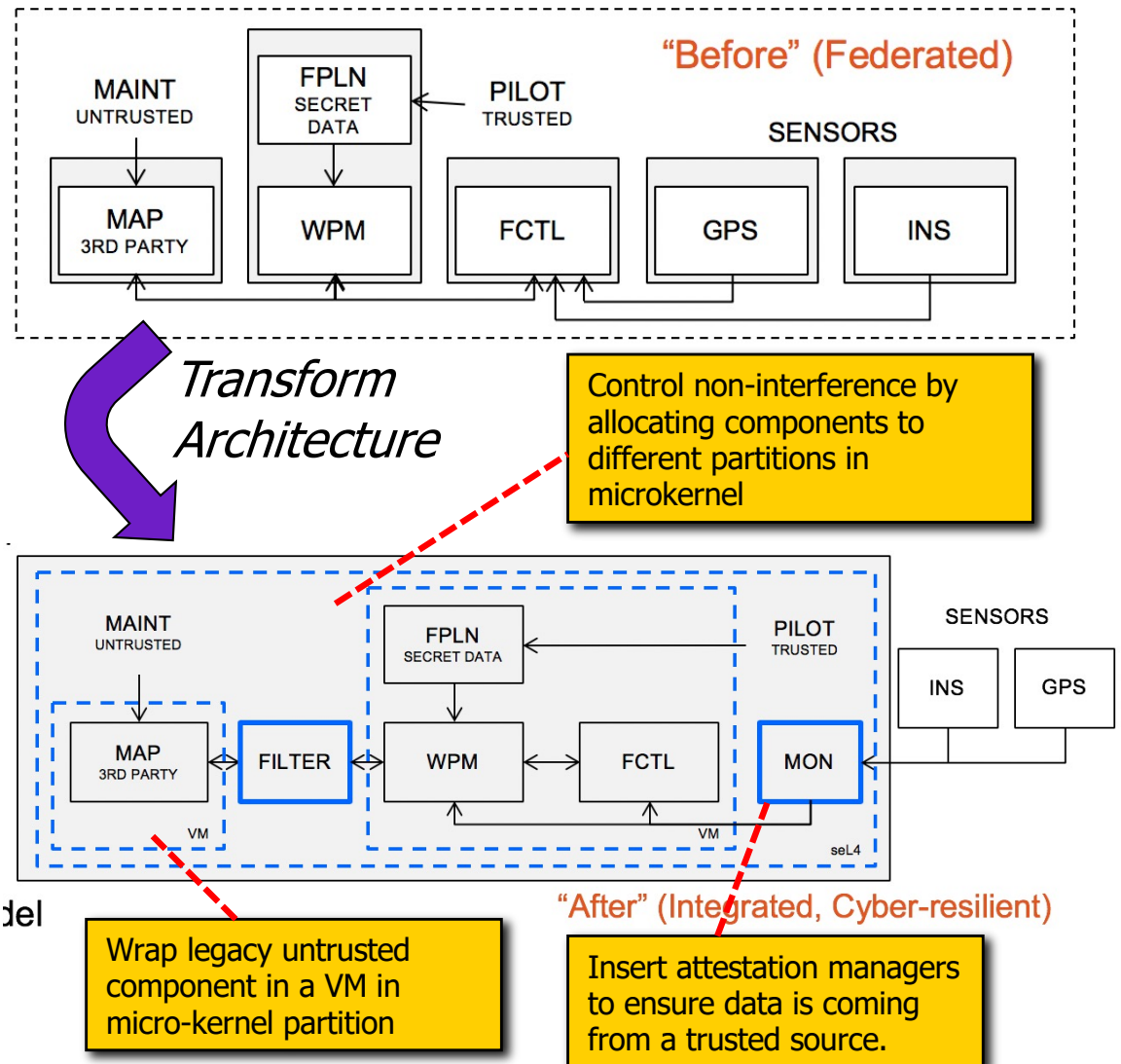
HAMR is being developed by Kansas State and Adventium Labs on a team led by Collins Aerospace (Darren Cofer) that includes Data61 and University of Kansas

- **Capture requirements** for cyber-resiliency
- **Analyze** design
- **Transform** design
- **Verify new design** against requirements

- **Build / Deploy**

seL4 verified micro-kernel technology is a core technology

HAMR Focus

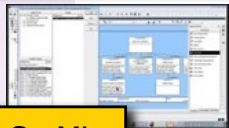


HAMR for seL4 Development

What does HAMR provide seL4 application developers?

A full systems engineering environment based on an standardized modeling language (AADL) with many accompanying analysis and verification tools + integration with industrial workflows

AADL-standardized "bridges" to industry workflows



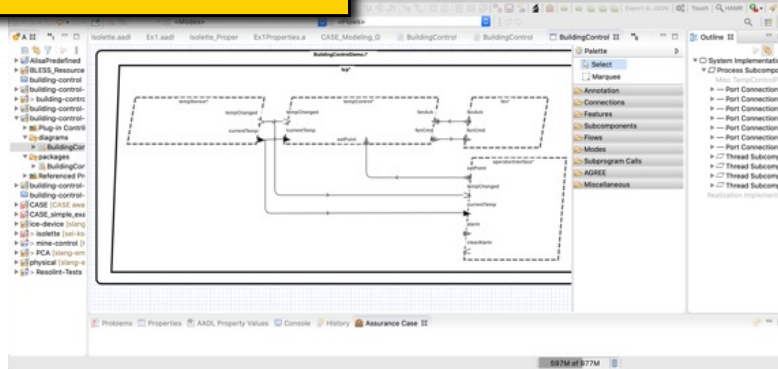
SysML



FACE

Systems Engineering

AADL OSATE IDE

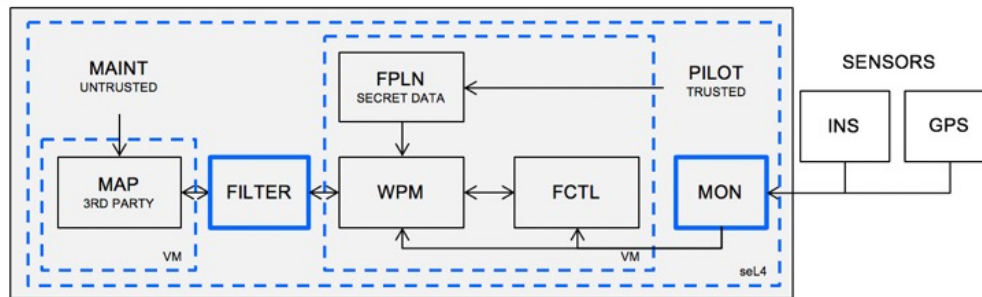


OSATE + HAMR Capabilities

- Software/Hardware/Middleware Modeling
- Hazard Analysis
- Information Flow Analysis
- Timing / Scheduleability
- Component Contracts + Verification
- Unit Testing
- Simulation and Execution Visualization

seL4 Deployment

CAMKES Specification



del

"After" (Integrated, Cyber-resilient)

Data61 tool for component-oriented specification of seL4 partitioning and inter-partition communication

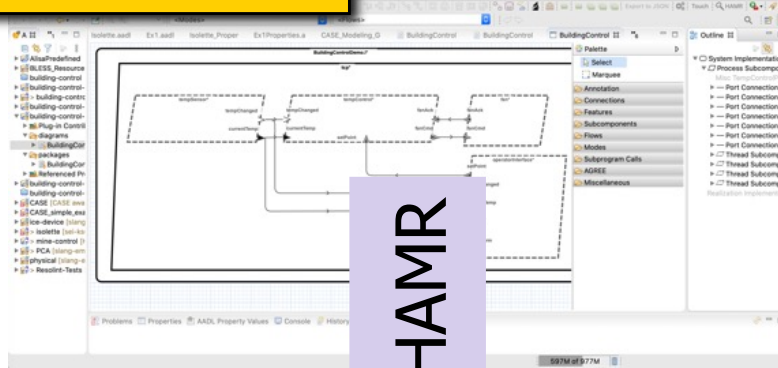
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Systems Engineering

AADL OSATE IDE



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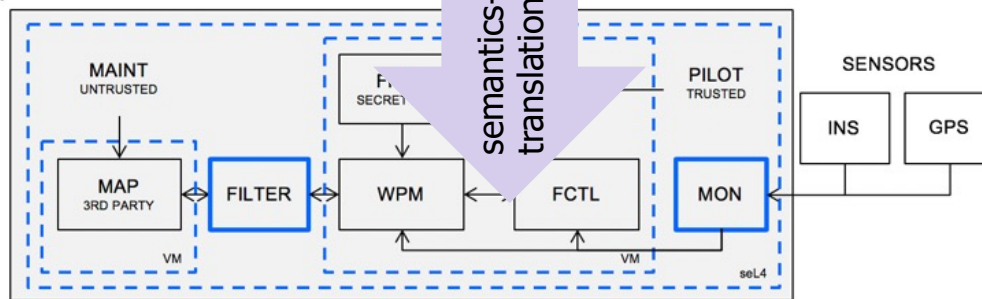
HAMR

semantics-preserving translation

Ensuring AADL modeling, analysis, and verification results carry over to implementation

seL4 Deployment

CAMKES Specification



"After" (Integrated, Cyber-resilient)

A HAMR Goal:
 Framework for building **verified applications** on top of seL4 verified infrastructure
 (DARPA, US Army, AFRL SBIRs w/ Adventium)

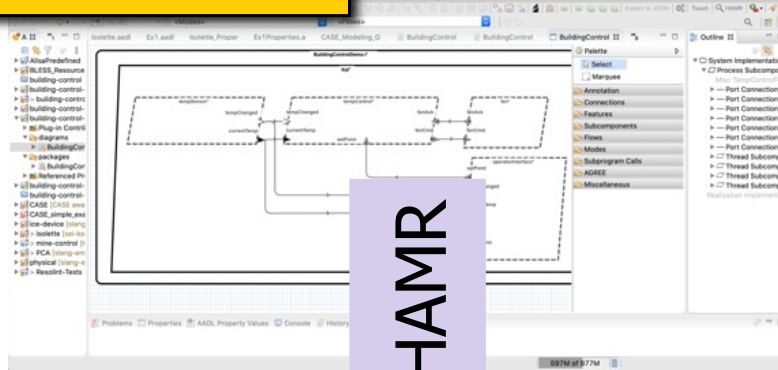
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Systems Engineering

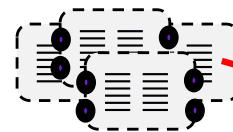
AADL OSATE IDE



OSATE + HAMR Capabilities

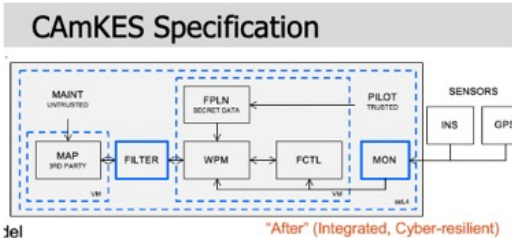
- Software/Hardware/Middleware Modeling
- Hazard Analysis
- Information Flow Analysis
- Timing / Scheduleability
- Component Contracts + Verification
- Unit Testing
- Simulation and Execution Visualization

semantics-preserving translation



Component application logic programmed in **C** or **Slang** (Scala subset and compilable to C)

seL4 Deployment



Linux Deployment



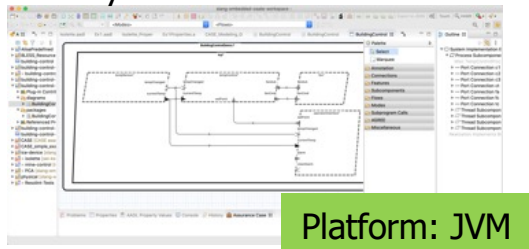
JVM Deployment



Example HAMR Multiple-Platform Workflow on DARPA CASE

Rapid prototyping / agile development progression to seL4 deployment

Initial system model



Slang mock-up of component functions

- Initial system model
- System message types designed
- Integration planned
- Component unit testing

HAMR JVM Simulation and Visualization



Workflow

HAMR JVM Event Stream Filtering

HAMR JVM platform enables very flexible filtering and visualization of inter-component communication, with the ability to filter on different categories of messages, ports, components, etc.

The screenshot displays the HAMR JVM Event Stream Filtering interface. At the top, there is a menu titled "Captures" with a search bar containing "everything". A dropdown menu is open, listing various filter categories: "manual-periodic-only", "manual-sporadic-only" (highlighted in blue), "manual-start-only-live-5-sec", "manual-stop-only", "out-port-only", "periodic-only", "sporadic-only", and "temp-sensor-alarm". A red dotted line points from the "manual-sporadic-only" option to a yellow callout box on the right that reads: "Menu of event stream filters – automatically populated from user-defined filter methods defined in framework".

The main area of the interface shows an "Event stream" of captured messages. Each message entry includes the bridge name, port name, time, and data. The messages are filtered to show only "Sporadic(1000)" events. A red dotted line points from the "Event stream" label at the bottom right to the stream content.

```
Bridge: BuildingControlDemo_i_Instance_tcp_tempControl (1) Sporadic(1000)
Port: BuildingControlDemo_i_Instance_tcp_tempControl_currentTemp (1) Event In
Time: 40 s 281 ms
Data: Temperature_Payload(Temperature(87.33246f, Fahrenheit))

Bridge: BuildingControlDemo_i_Instance_tcp_operatorInterface (3) Periodic(1000)
Port: BuildingControlDemo_i_Instance_tcp_operatorInterface_currentTemp (8) Event In
Time: 40 s 281 ms
Data: Temperature_Payload(Temperature(87.33246f, Fahrenheit))

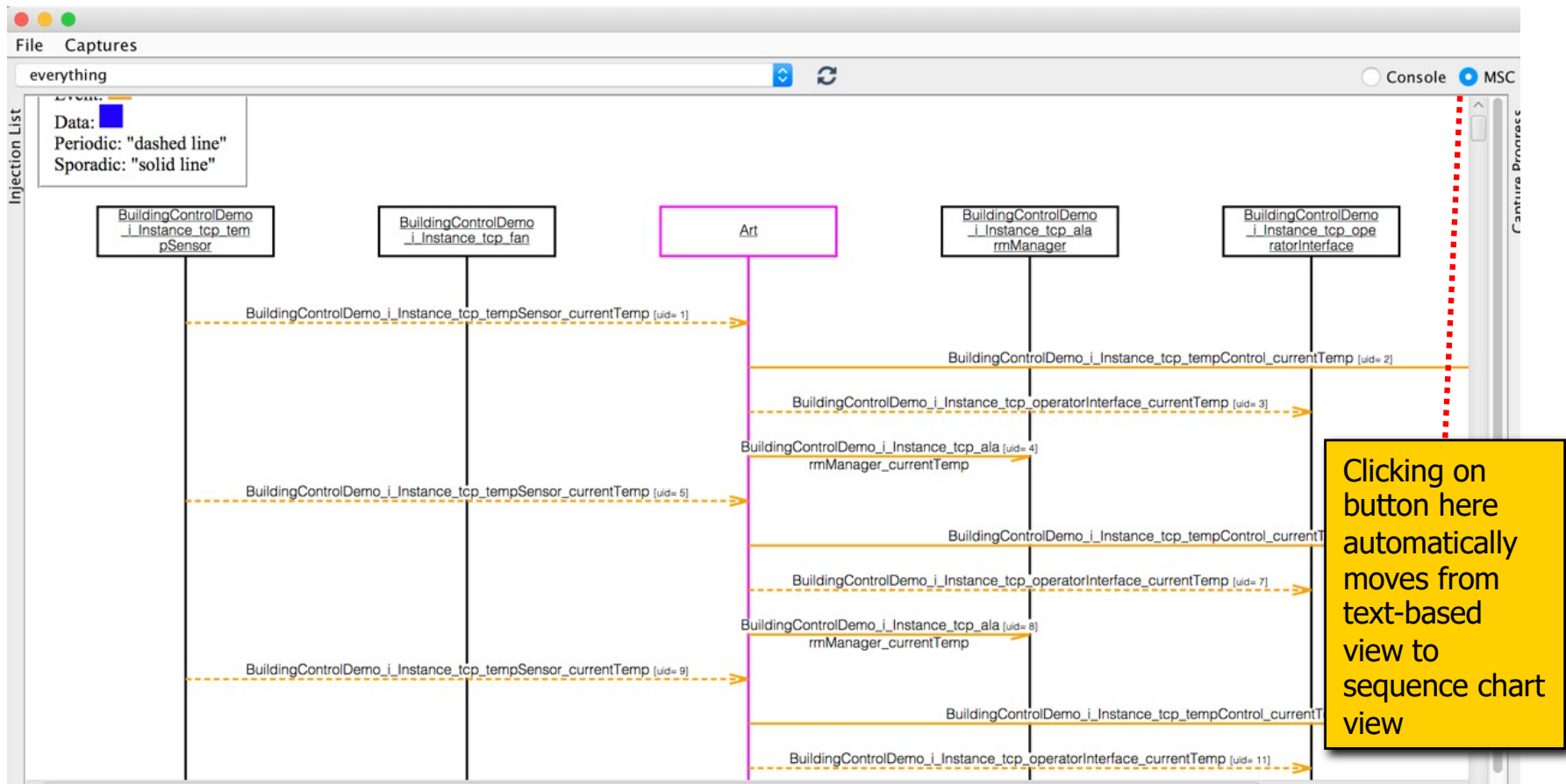
Bridge: BuildingControlDemo_i_Instance_tcp_alarmManager (4) Sporadic(1000)
Port: BuildingControlDemo_i_Instance_tcp_alarmManager_currentTemp (12) Event In
Time: 40 s 281 ms
Data: Temperature_Payload(Temperature(87.33246f, Fahrenheit))

Bridge: BuildingControlDemo_i_Instance_tcp_tempSensor (0) Periodic(1000)
Port: BuildingControlDemo_i_Instance_tcp_tempSensor_currentTemp (0) Event Out
Time: 41 s 281 ms
Data: Temperature_Payload(Temperature(88.95927f, Fahrenheit))

Bridge: BuildingControlDemo_i_Instance_tcp_tempControl (1) Sporadic(1000)
Port: BuildingControlDemo_i_Instance_tcp_tempControl_currentTemp (1) Event In
Time: 41 s 281 ms
Data: Temperature_Payload(Temperature(88.95927f, Fahrenheit))
```


HAMR JVM Execution Visualizations

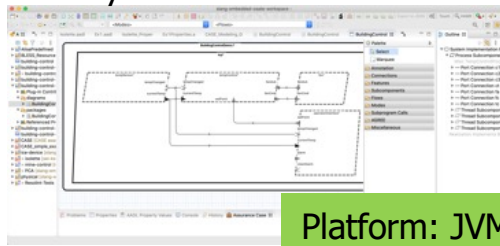
HAMR JVM provides ability to visualize system execution – below, dynamically generated/updated message sequence charts (filterable) of inter-component communication



Example HAMR Multiple-Platform Workflow on DARPA CASE

Rapid prototyping / agile development progression to seL4 deployment

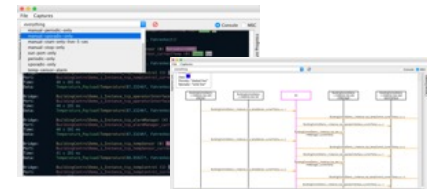
Initial system model



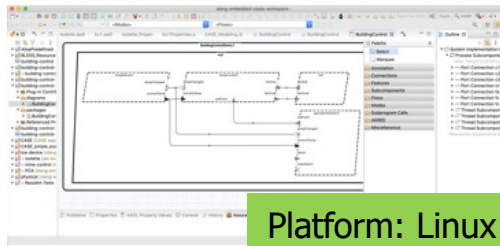
Slang mock-up of component functions

- Initial system model
- System message types designed
- Integration planned
- Component unit testing

HAMR JVM Simulation and Visualization

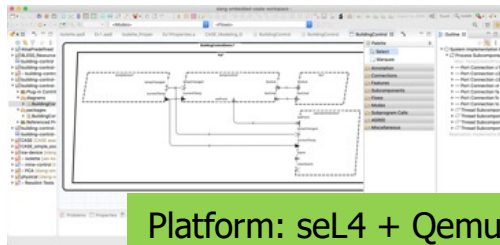


Workflow



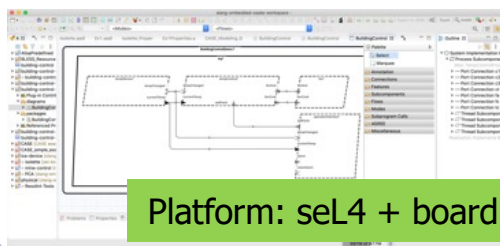
C coding of component functions (hand-written or translated from Slang)

- Testing of C components
- Mock up of VM functions
- Initial System Testing



C components

- Design of domain schedule
- Integration of VMs
- Enhanced system testing



C components + drivers, communication stack

- Integration of drivers
- Final system testing
- Penetration testing

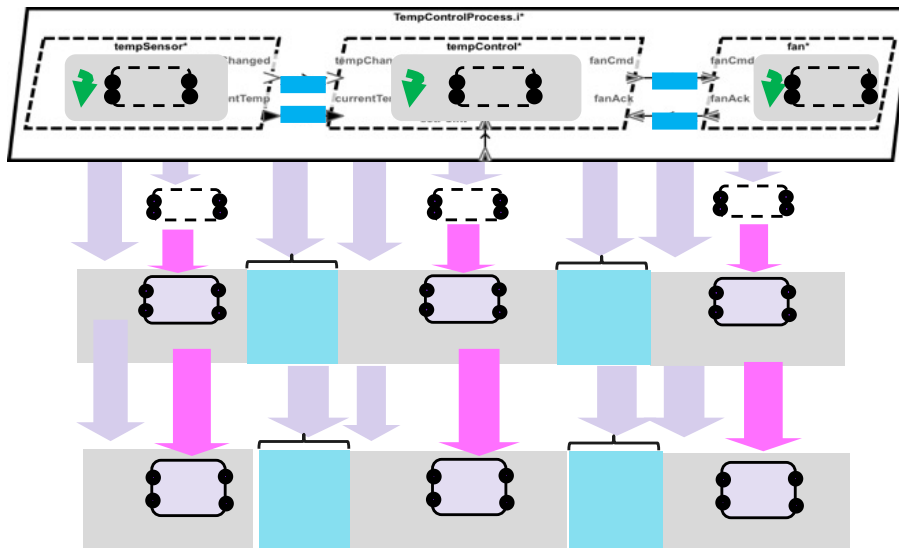
Notions of Composition

Horizontal Composition

...composing components via AADL port connections at the application layer



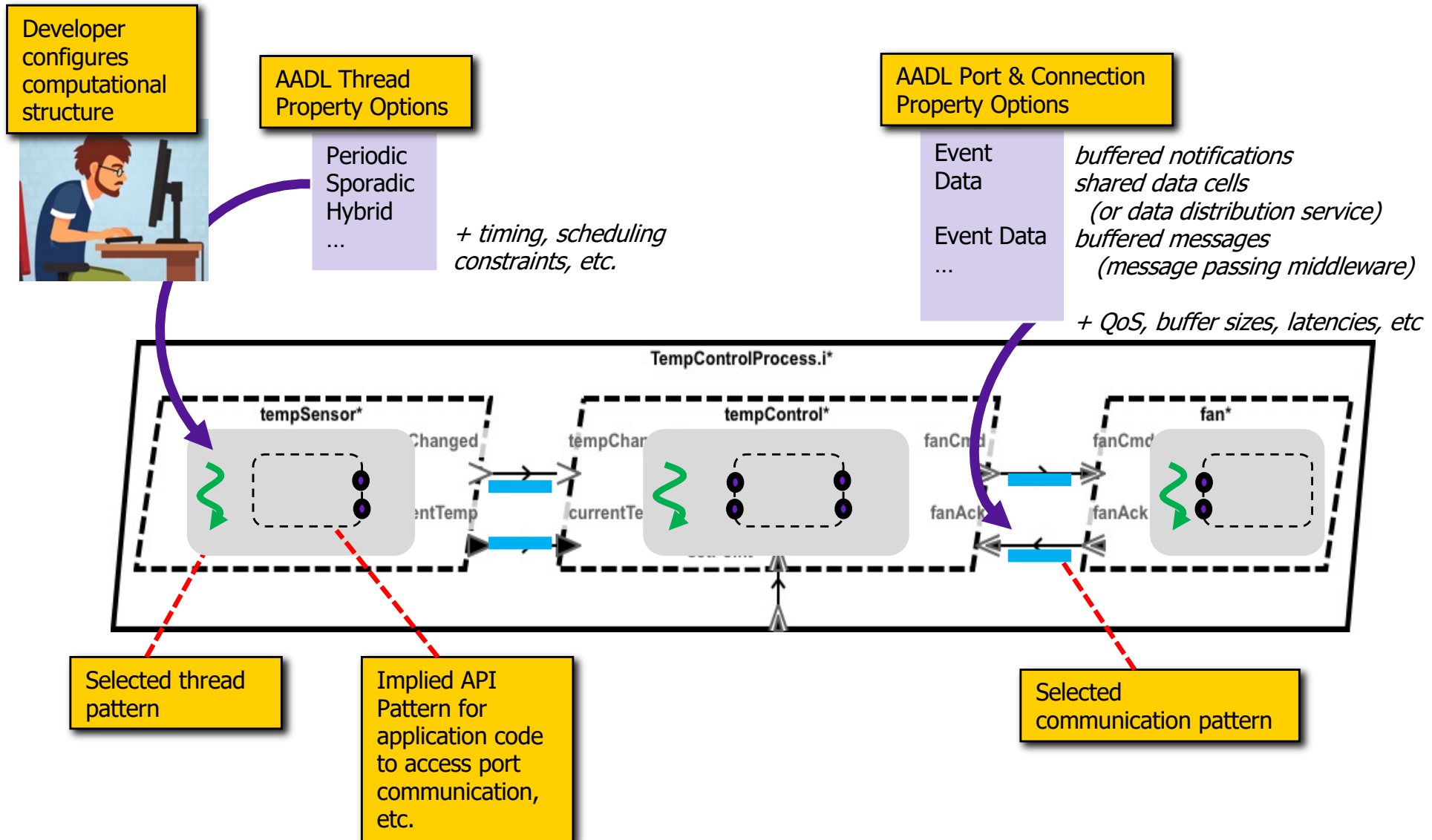
Vertical Composition



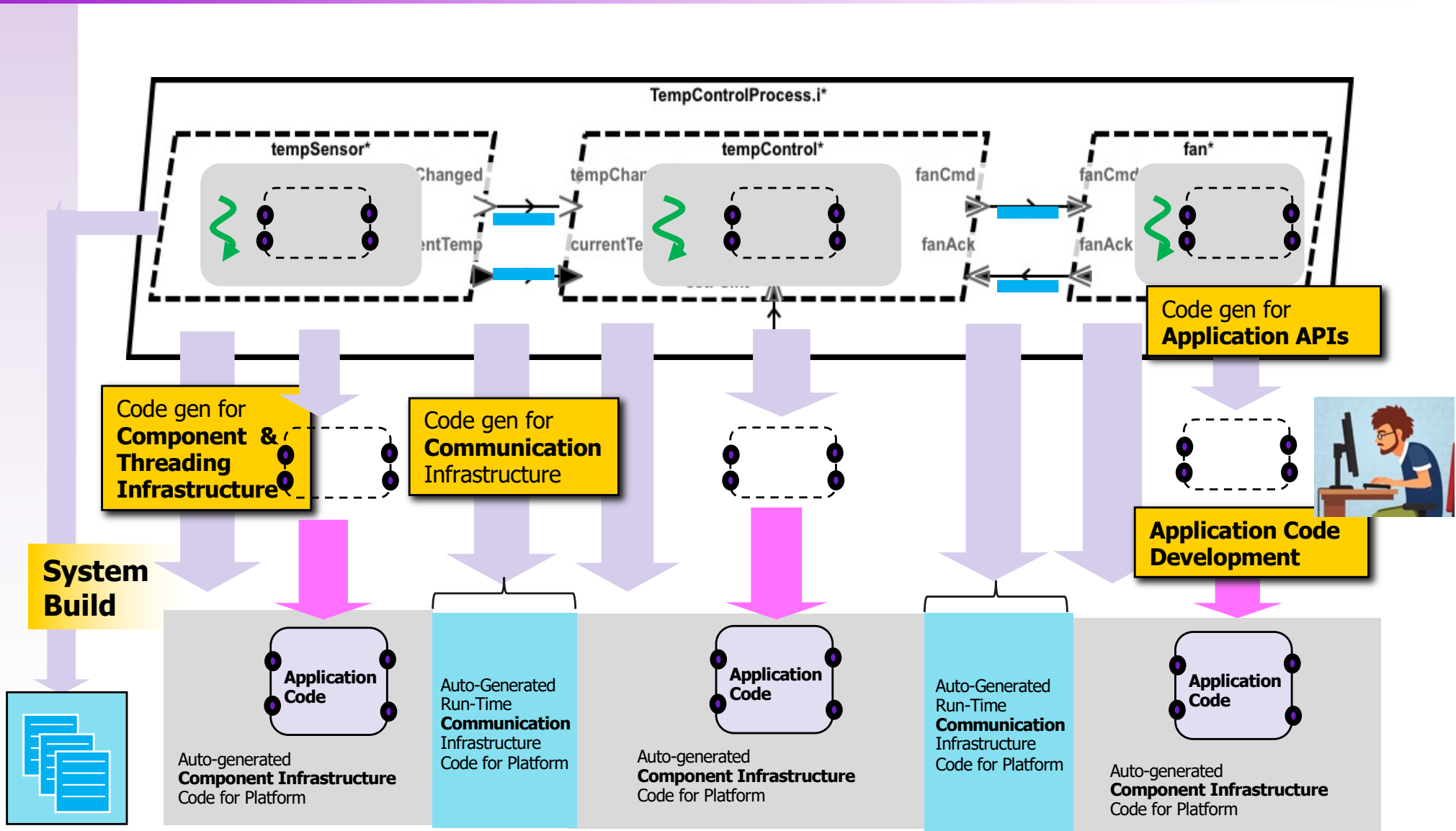
...composing multiple layers of abstractions for threading and communication (refinements)

...ensuring consistency in threading and communication structure to ensure correctness and enable horizontal composition at lower levels

AADL Computational Model

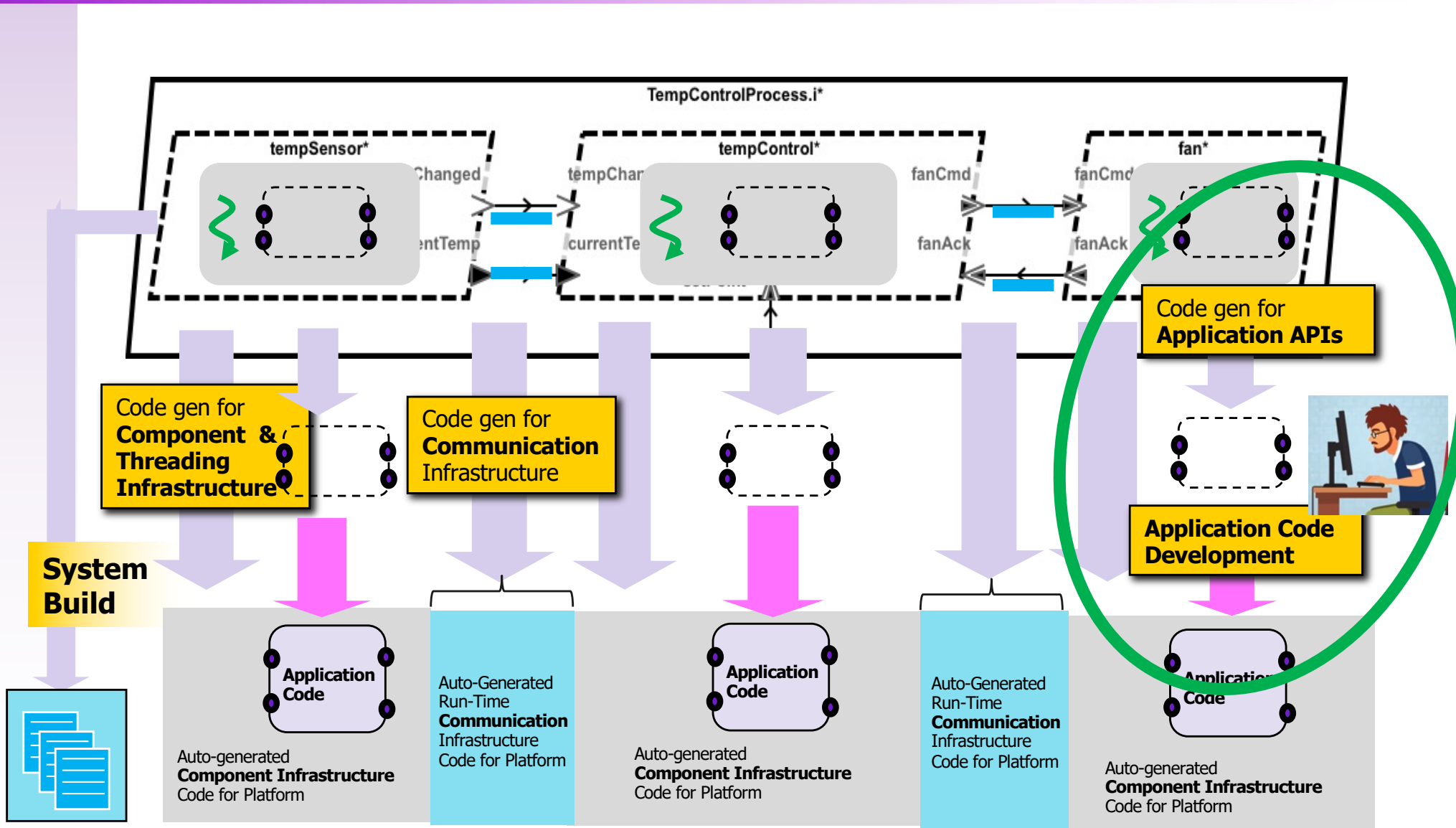


HAMR Code Generation



Platform configuration information

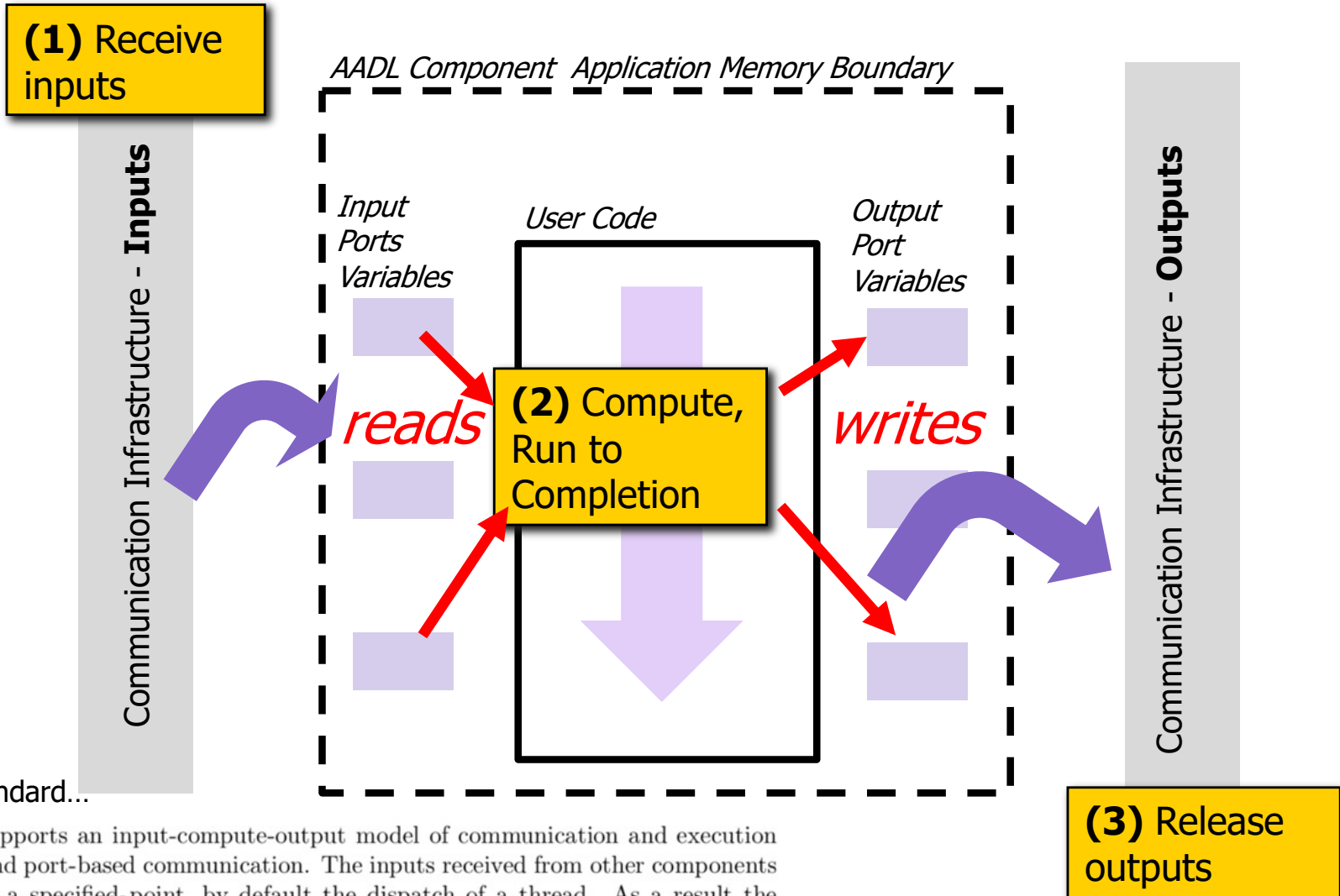
HAMR Code Generation



Platform configuration information

Port Semantics and Thread Execution

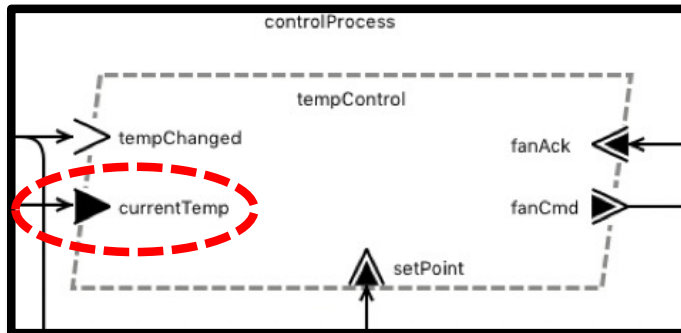
On each dispatch, AADL threads follow a well-known **input-compute-output** pattern for real-time tasks that aid analysis and verification...



From AADL standard...

(2) AADL supports an input-compute-output model of communication and execution for threads and port-based communication. The inputs received from other components are frozen at a specified point, by default the dispatch of a thread. As a result the

Platform-Independent Port APIs Generated from AADL Model



...For each port, HAMR generates an API for communicating over that port. These link to auto-generated implementations of port communication for the chosen platform

APIs for Port Communication

Reference parameter for receiving port value.

auto-generated

Status value indicating if operation succeeded

```
bool api_get_currentTemp(Temp value);
bool api_get_fanAck(FanAck_Type *value);
bool api_get_setPoint(SetPoint value);
void api_send_fanCmd(FanCmd_Type value);
bool api_get_tempChanged();
```

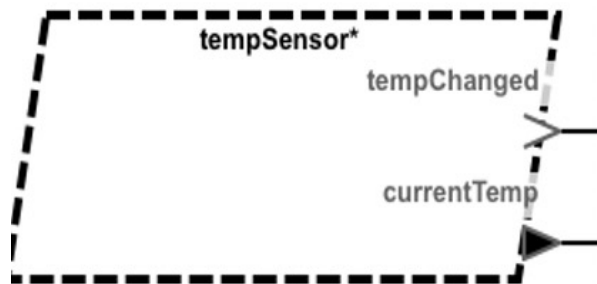
Implementations for Port Communication APIs for target platform

Linux

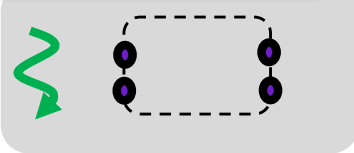
seL4

Uses CAmkES + HAMR-generated "glue code"

Platform-Independent Thread Structure Generated from AADL Model - *Periodic*



AADL Model
Implied Semantics



auto-generated

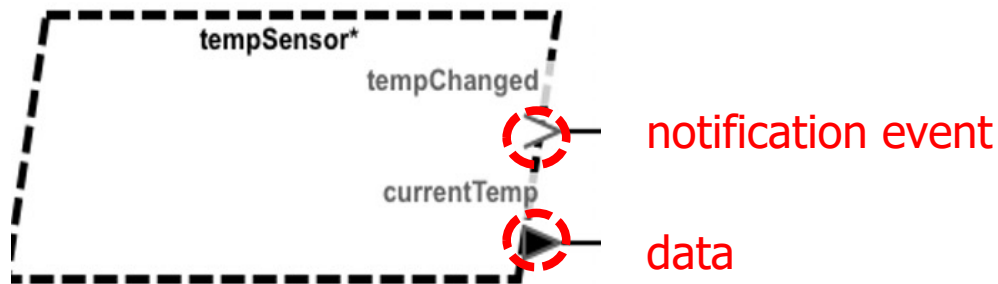


Application Code
Skeleton in C

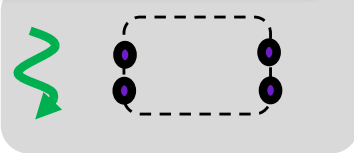
Periodic thread – skeleton for application logic

```
Unit timeTriggered() {  
    ...  
}
```

Platform-Independent Thread Structure Generated from AADL Model - *Periodic*

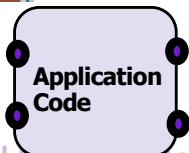


AADL Model
Implied Semantics



auto-generated

Application
Code
Development



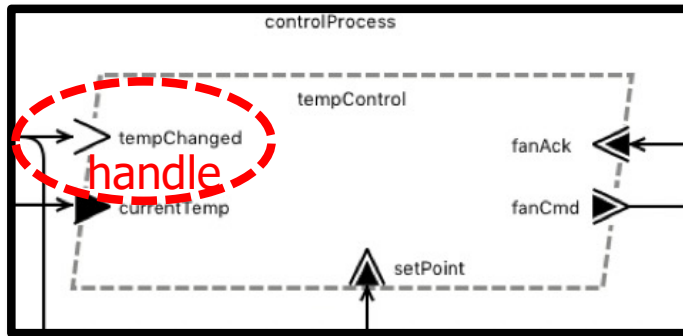
Periodic thread – skeleton filled with application logic

```
Unit timeTriggered() {  
  DeclNew_Temperature(currTemp);  
  
  // read current temp from hardware sensor  
  senseTemperature(&currTemp);  
  
  // take action if temperature has changed  
  if(lastTemperature.degrees != currTemp.degrees) {  
    lastTemperature = currTemp;  
    api_send_currentTemp(&lastTemperature);  
    api_send_tempChanged();  
  }  
}
```

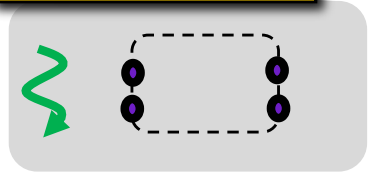
Put new temp value
on output data port

Notify consumers
that temperature
changed

Platform-Independent Thread Structure Generated from AADL Model - *Sporadic*



AADL Model
Implied Semantics



auto-generated

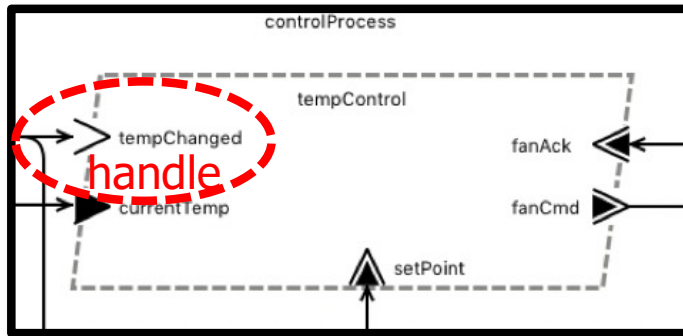


Application Code
Skeleton in C

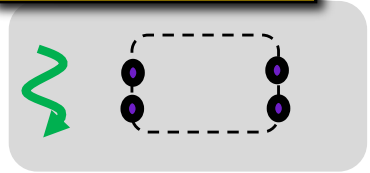
Sporadic thread – skeleton for application logic – event handlers

```
void TempControl_tempChanged(void) {  
    ...  
}
```

Platform-Independent Thread Structure Generated from AADL Model - *Sporadic*



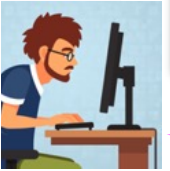
AADL Model
Implied Semantics



auto-generated



Application
Code
Development



Sporadic thread – skeleton for application logic – event handlers

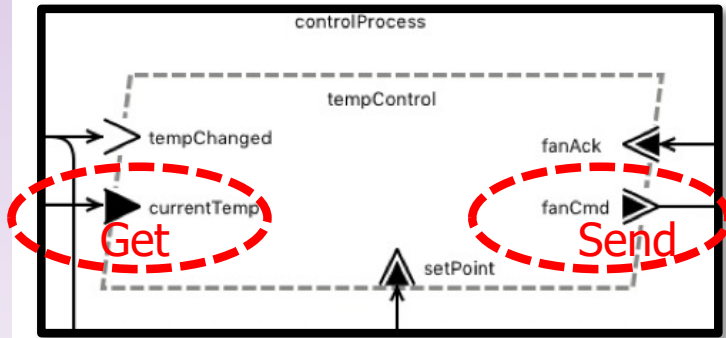
```

void tempChanged(void) {
    DeclTemp(currTemp); // macro to allocate Temp in stack

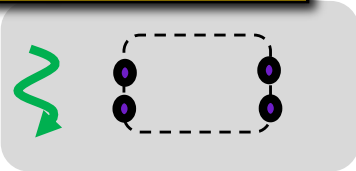
    if (api_get_currentTemp(&currTemp)) {
        struct Temp currTempInF = convertToF(&currTemp);

        if (currTempInF.degrees > setPoint.high.degrees) {
            api_send_fanCmd(FanCmd_On);
        } else
        if (currTempInF.degrees < setPoint.low.degrees) {
            api_send_fanCmd(FanCmd_Off);
        }
    }
}
    
```

Platform-Independent Thread Structure Generated from AADL Model - *Sporadic*



AADL Model
Implied Semantics



auto-generated

Application
Code
Development



Get Send -- Kansas State

Sporadic thread – skeleton for application logic – event handlers

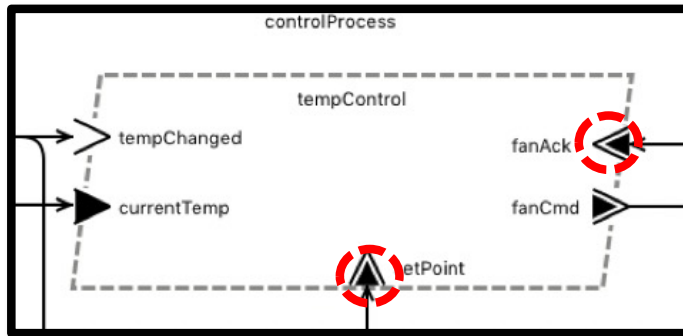
```
void tempChanged(void) {
    DeclTemp(currTemp); // macro to allocate T
    if (api_get_currentTemp(&currTemp)) {
        struct Temp currTempInF = convertToF(&currTemp);

        if (currTempInF.degrees > setPoint.high.degrees) {
            api_send_fanCmd(FanCmd_On);
        } else
        if (currTempInF.degrees < setPoint.low.degrees) {
            api_send_fanCmd(FanCmd_Off);
        }
    }
}
```

Get current
temperature

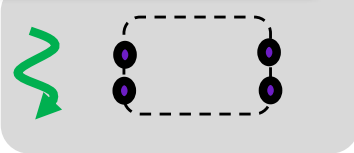
Send
command to
fan

Platform-Independent Thread Structure Generated from AADL Model - *Sporadic*



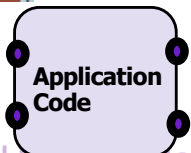
...HAMR also generates handlers for the remaining input event data ports

AADL Model
Implied Semantics



auto-generated

Application
Code
Development



Sporadic thread – setPoint– event handler

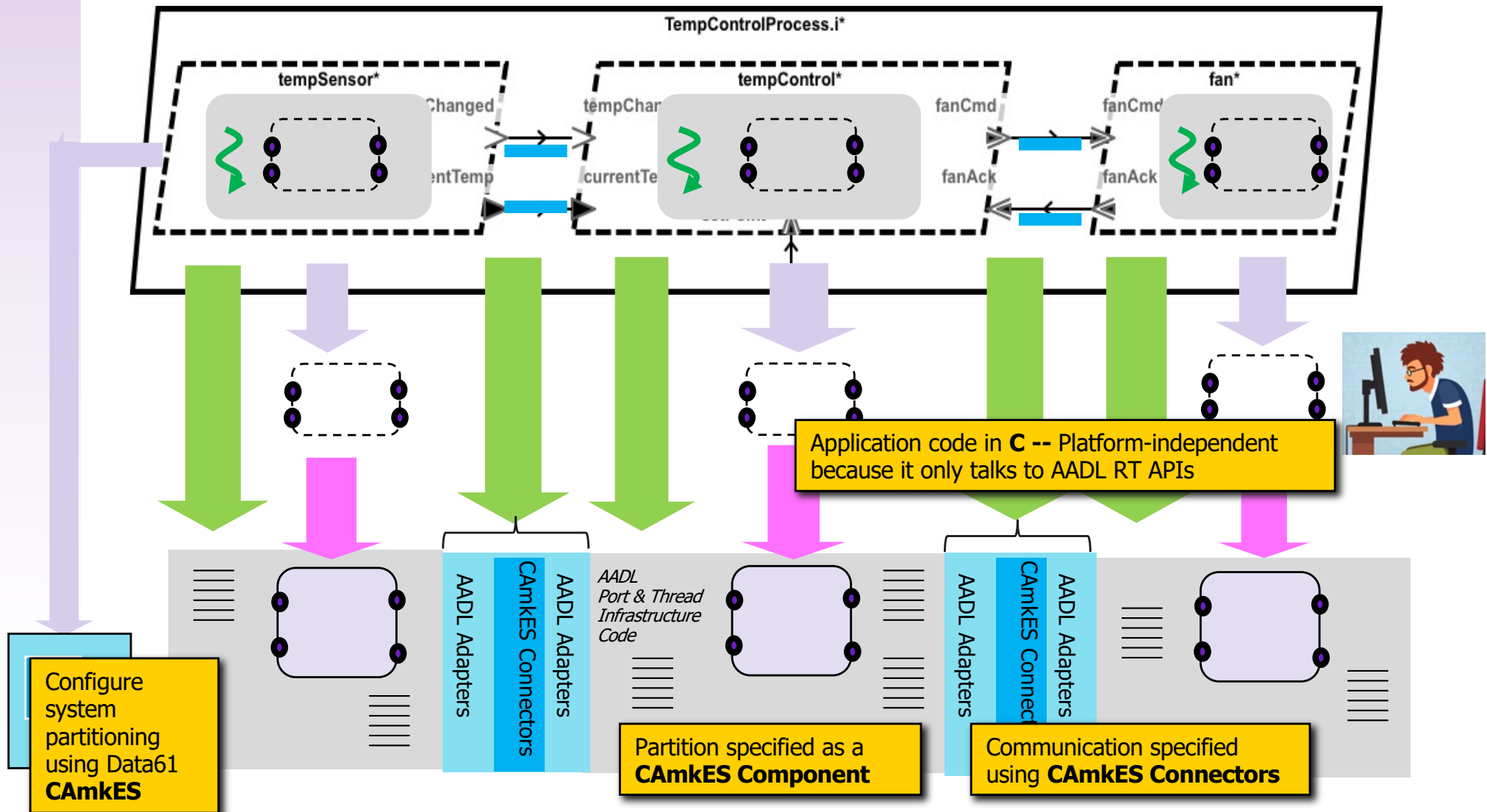
```
void handleSetPoint(SetPoint value) {
    ...
}
```

Sporadic thread – fanAck– event handler

```
void handlefanAck(FanAck_Type value) {
    ...
}
```

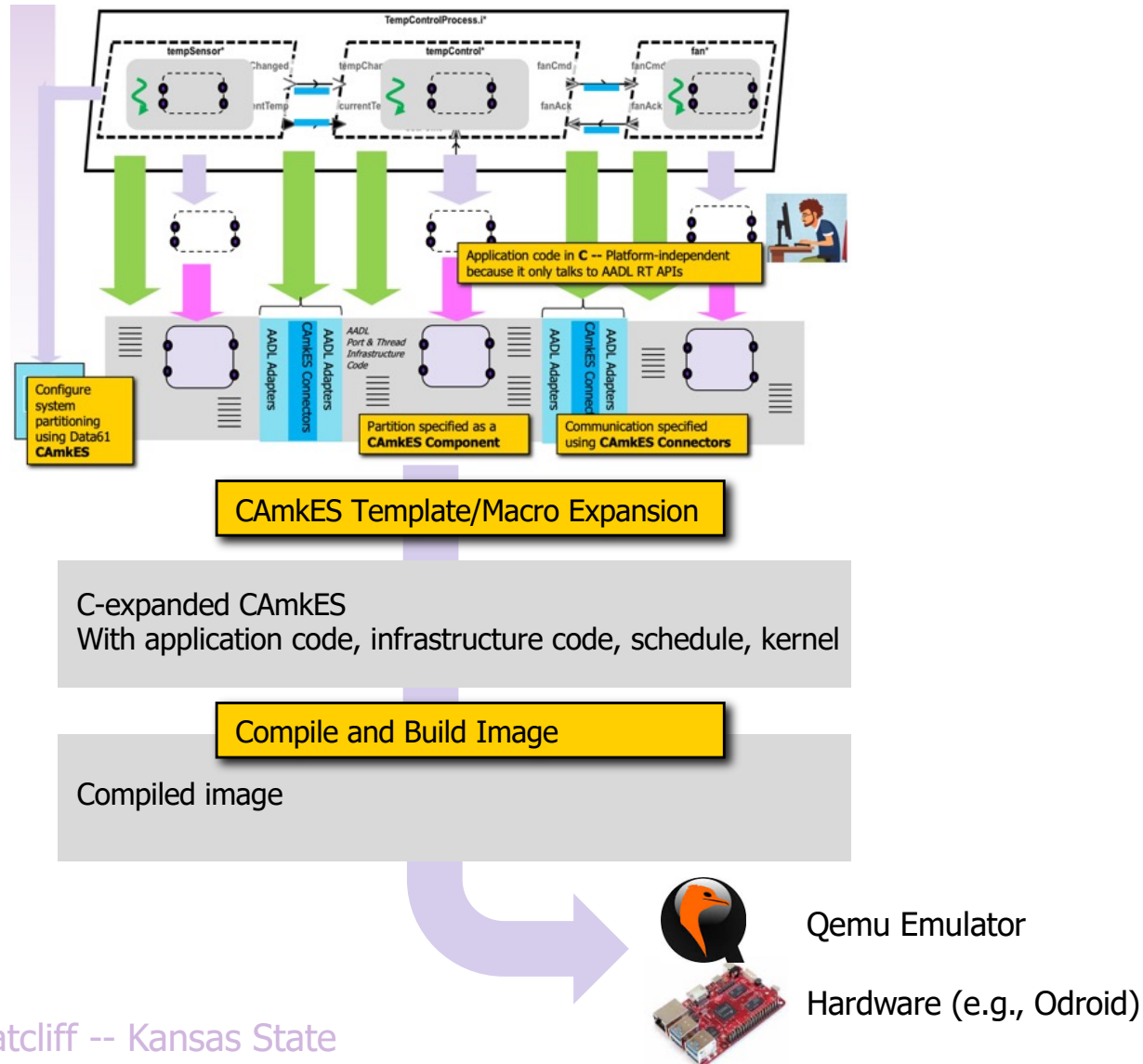
HAMR Code Generation seL4 Platform

HAMR instantiation for C-based development on **seL4 microkernel** (e.g., DARPA CASE)



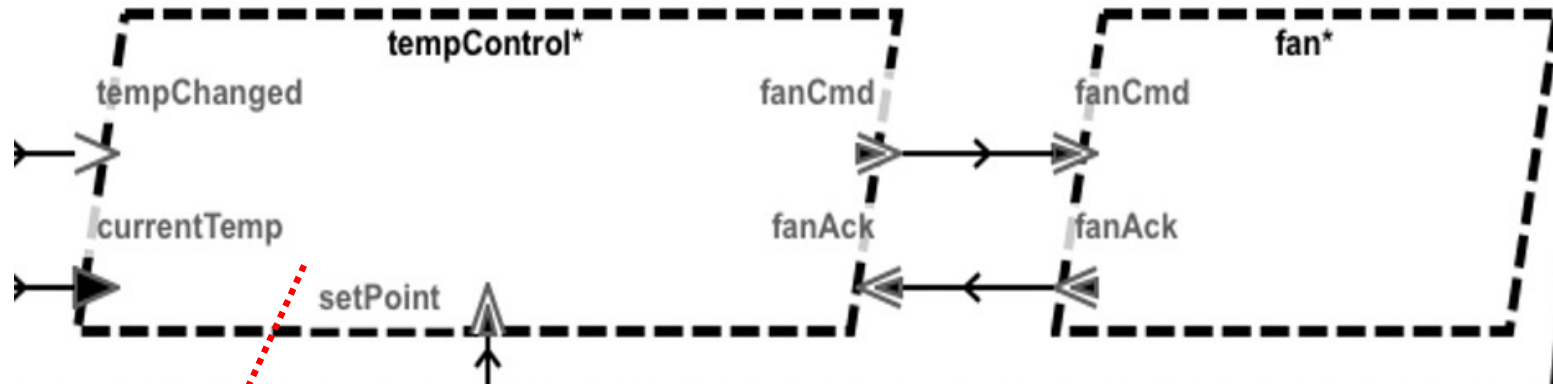
HAMR Code Generation seL4 Platform

HAMR utilizes the Data61 CAMkES framework to create the final build for deployment



CAmkES seL4 Configuration

AADL and Platform Independent Application Code



seL4 Platform Configuration Using CAmkES (auto-generated by HAMR)

```
component TempControl {
```

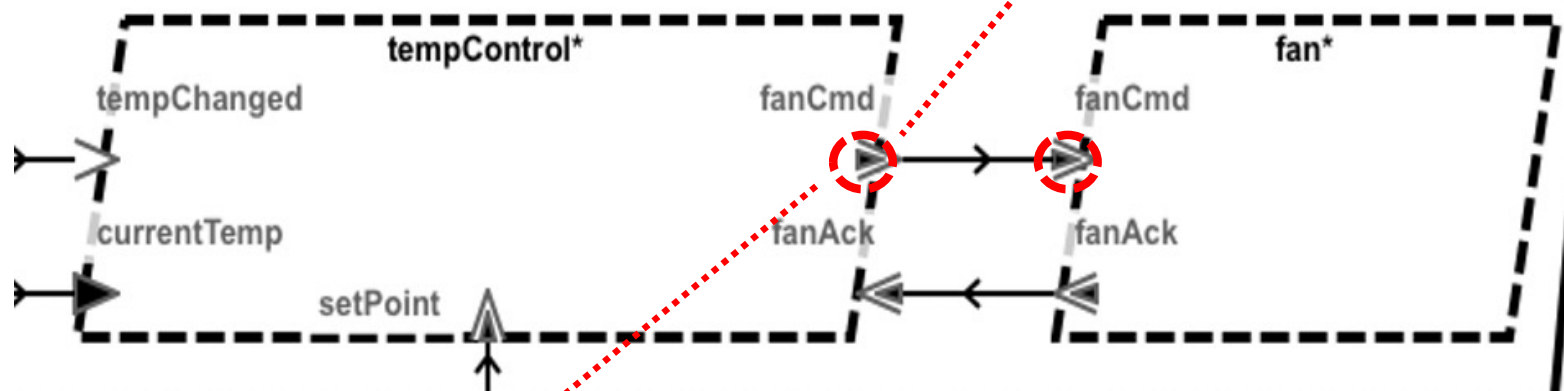
```
component Fan {
```

For each
AADL thread
component
create an
seL4 partition

CAmkES seL4 Configuration

AADL Event Data port (message with payload)

AADL and Platform Independent Application Code



seL4 Platform Configuration Using CAmkES (auto-generated by HAMR)

```

component TempControl {
    emits ReceiveEvent
        fanCmd_notification;
    dataport DataContent
        fanCmd_queue;
    ...
}
    
```

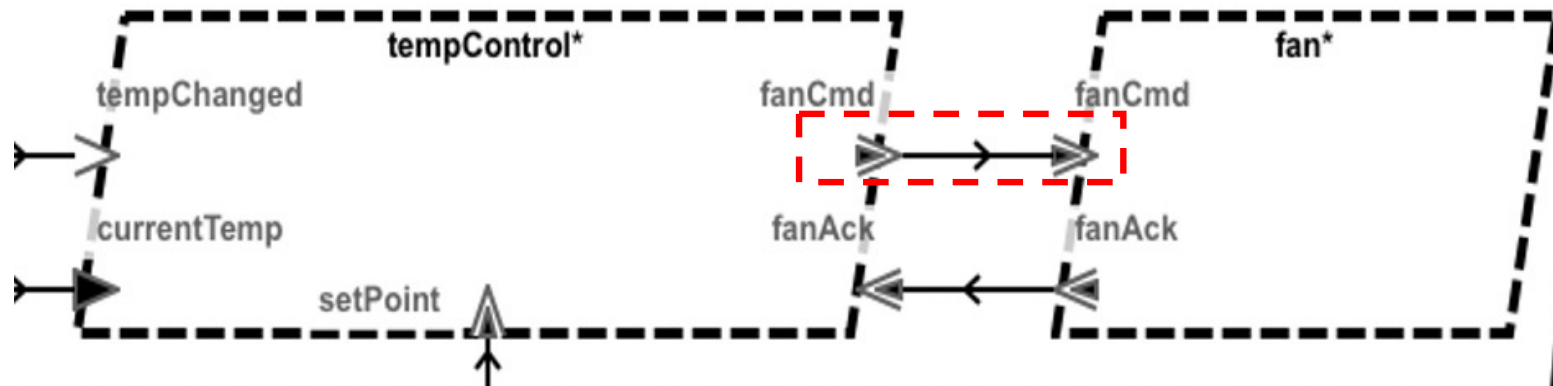
```

component Fan {
    consumes ReceiveEvent
        fanCmd_notification;
    dataport DataContent
        fanCmd_queue;
    ...
}
    
```

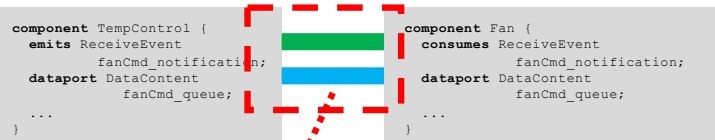
AADL Event Data port is represented using a CAmkES **notification** + **dataport** – introducing finer granularity as we move to platform

CAmkES seL4 Configuration

AADL and Platform Independent Application Code



seL4 Platform Configuration Using CAmkES (auto-generated by HAMR)

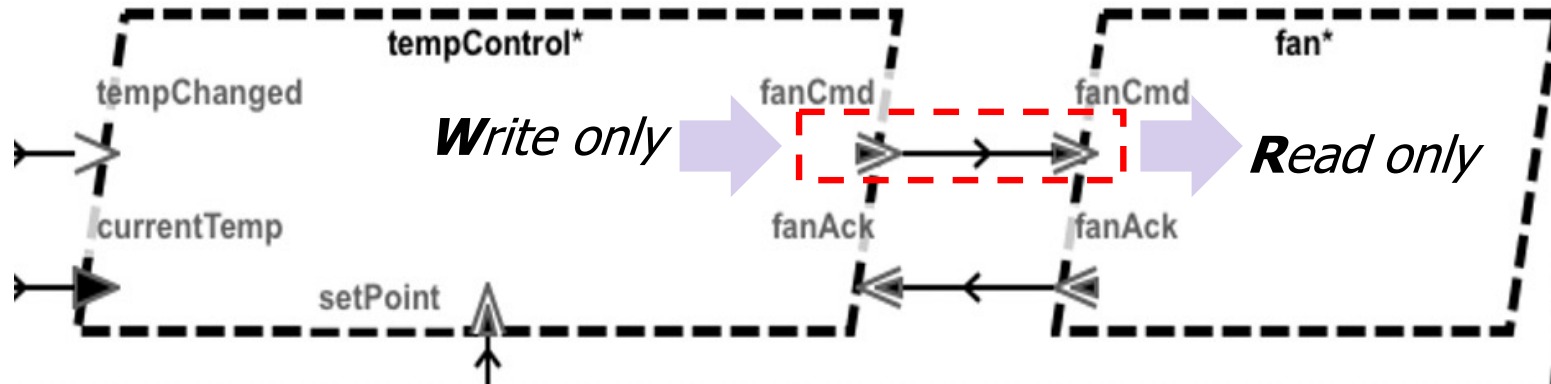


CAmkES **assembly** specifies system topology, including allowed communication between seL4 partitions

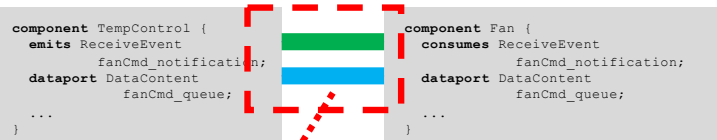
```
assembly {  
  composition {  
    component TempControl tempControl;  
    component Fan fan;  
    connection seL4Notification conn4(  
      from tempControl.fanCmd_notification,  
      to fan.fan_notification);  
    connection seL4SharedData conn5(  
      from tempControl.fanCmd_queue,  
      to fan.fanCmd_queue);  
    ... }  
}
```

CAmkES seL4 Configuration

AADL and Platform Independent Application Code



seL4 Platform Configuration Using CAmkES (auto-generated by HAMR)



```
assembly {
```

```
...
```

```
configuration {
```

```
tempControl.fanCmdqueue_access = "W";
```

```
fan.fanCmd_queue_access = "R";
```

```
...
```

```
}
```

```
}
```

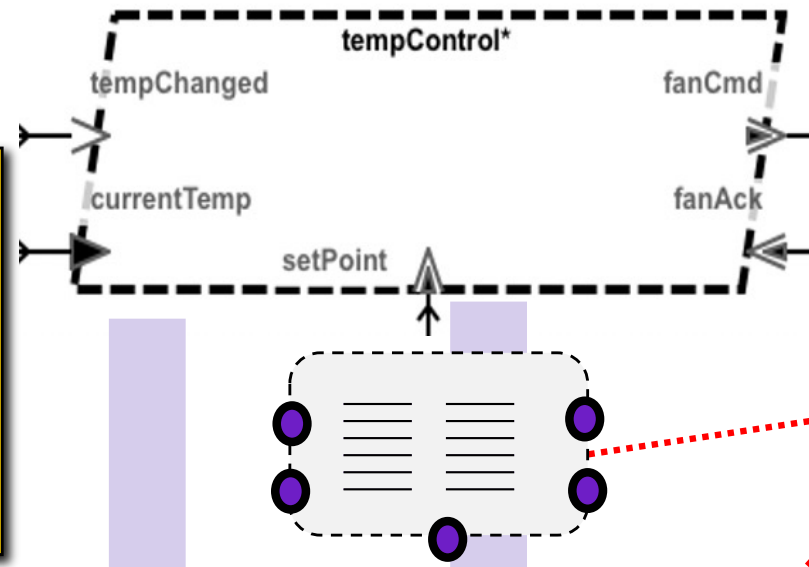
CAmkES **configuration** specifies seL4 capabilities for partition interaction.

Ensures that info flow implied by AADL model is achieved in deployed system using the formally verified seL4 info flow controls

Application Code Insertion

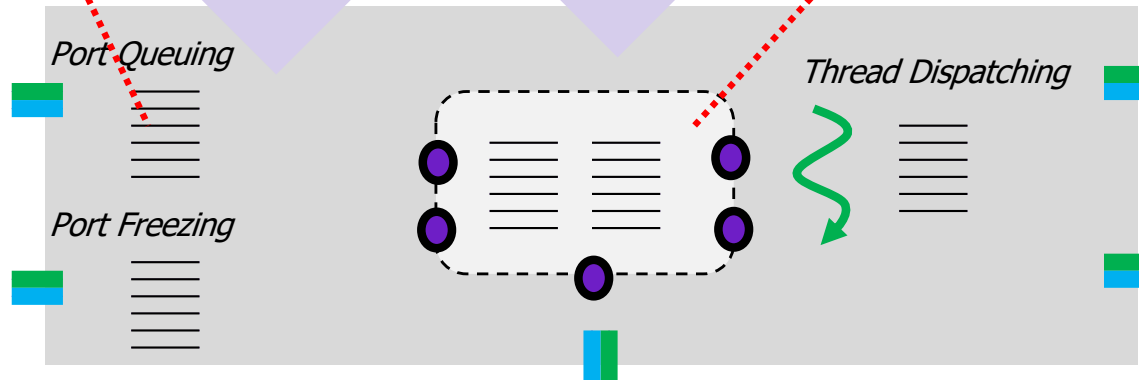
AADL with Component Application Code

HAMR generates adapter code that realizes the AADL port queuing and thread dispatch semantics in terms of CAMkES/seL4 primitives.



HAMR inserts AADL-compliant component application code into CAMkES/seL4 partition

seL4 as configured by CAMkES

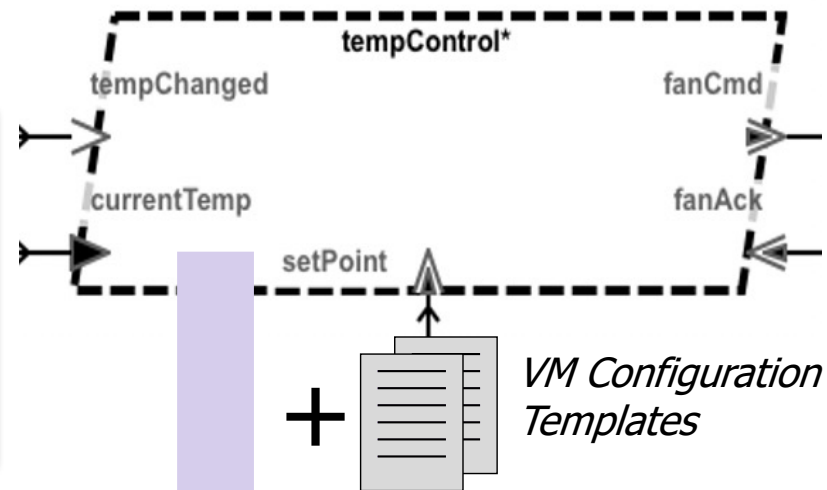


Note: HAMR also includes an option for **only** generating the CAMkES configuration from the AADL model -- leaving the developer to do what they want with all the internals of the CAMkES component (i.e., infrastructure code for AADL semantics is not included)

VM Insertion

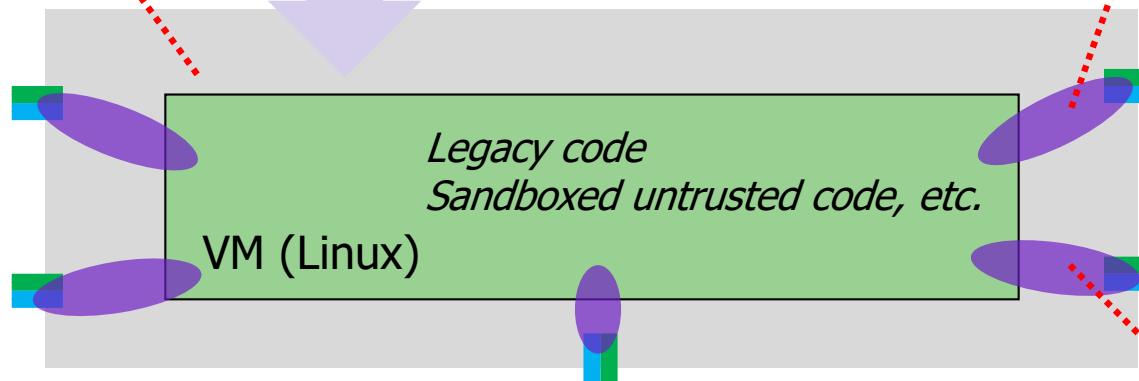
HAMR provides AADL modeling and code generation to automatically insert Linux virtual machines in to CAMkES/seL4 partitions (e.g., to host legacy or non-AADL-aligned code)

Guided by AADL model directives, HAMR can generate VM instances for an CAMkES/seL4 partition using pre-defined VM templates



While some manual configuration must be done, HAMR provides various forms of automated support, e.g., generating Linux device table mappings to seL4 ports

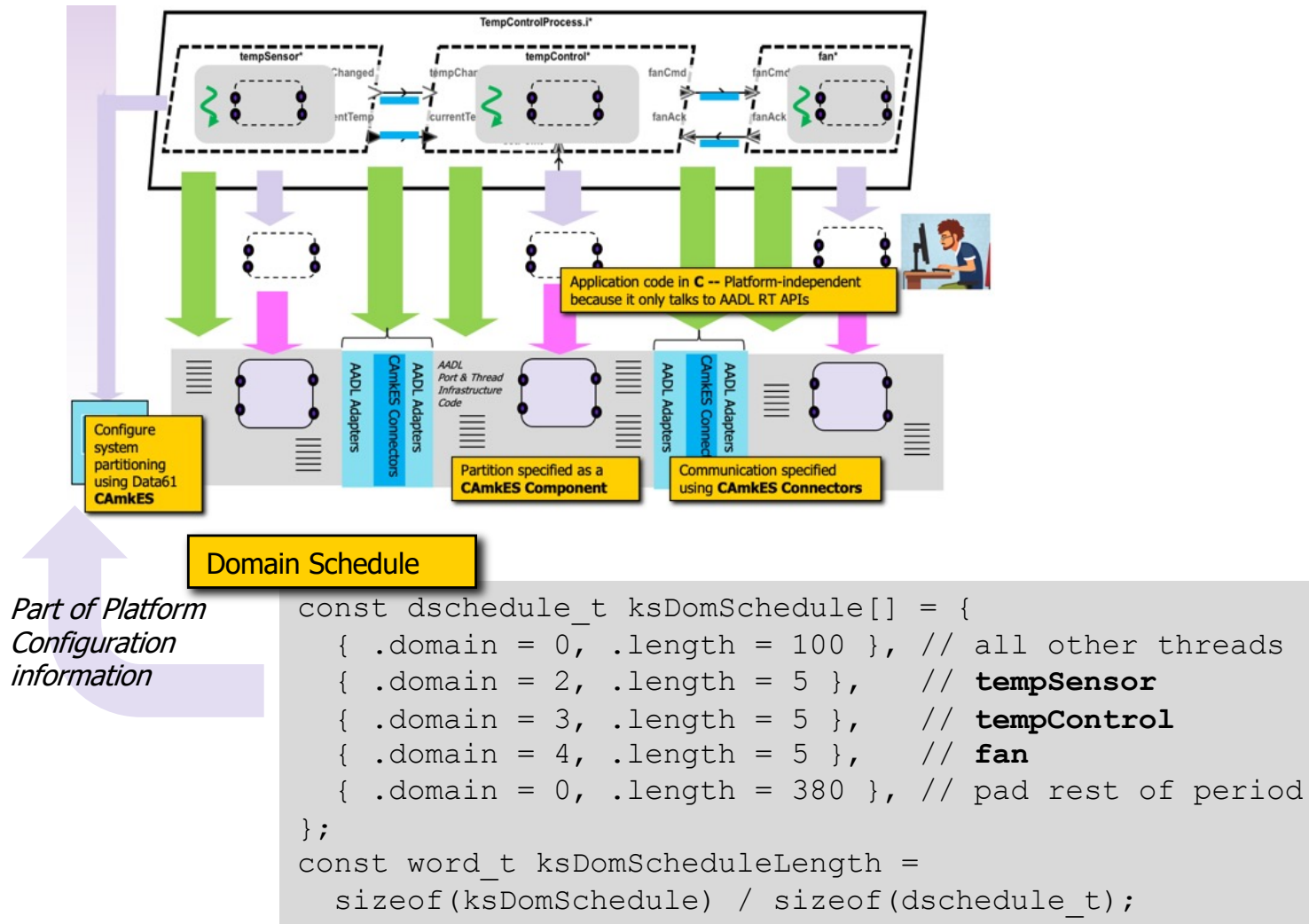
seL4 as configured by CAMkES



Linux device table mappings to seL4 ports

Static Schedule via Domain Schedule

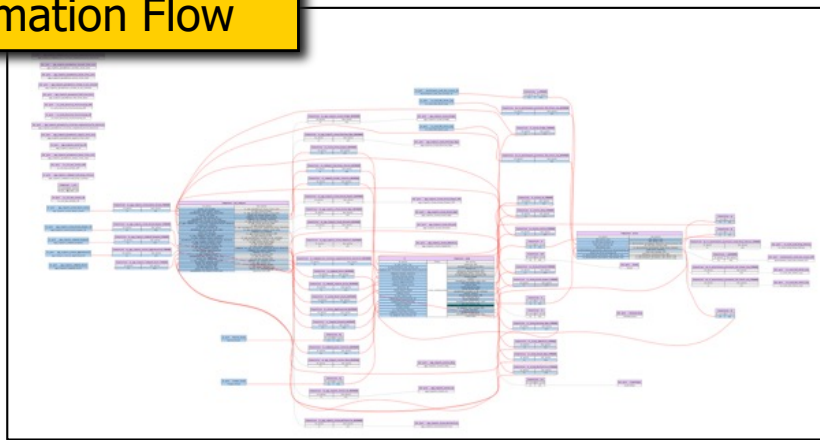
As a step towards the eventual use of seL4 MCS extensions, DARPA CASE is using the seL4 *domain schedule* to enforce temporal partitioning (see Todd Carpenter's talk in Assured Systems II session)



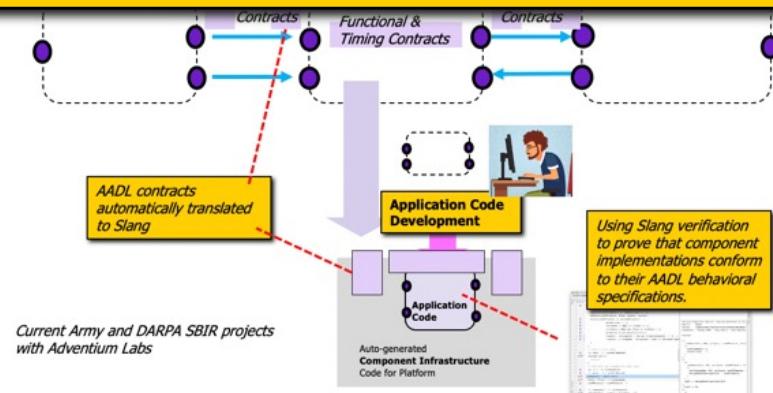
Up Next

Analyses and Verification enabled by planning for compositionality...

Information Flow

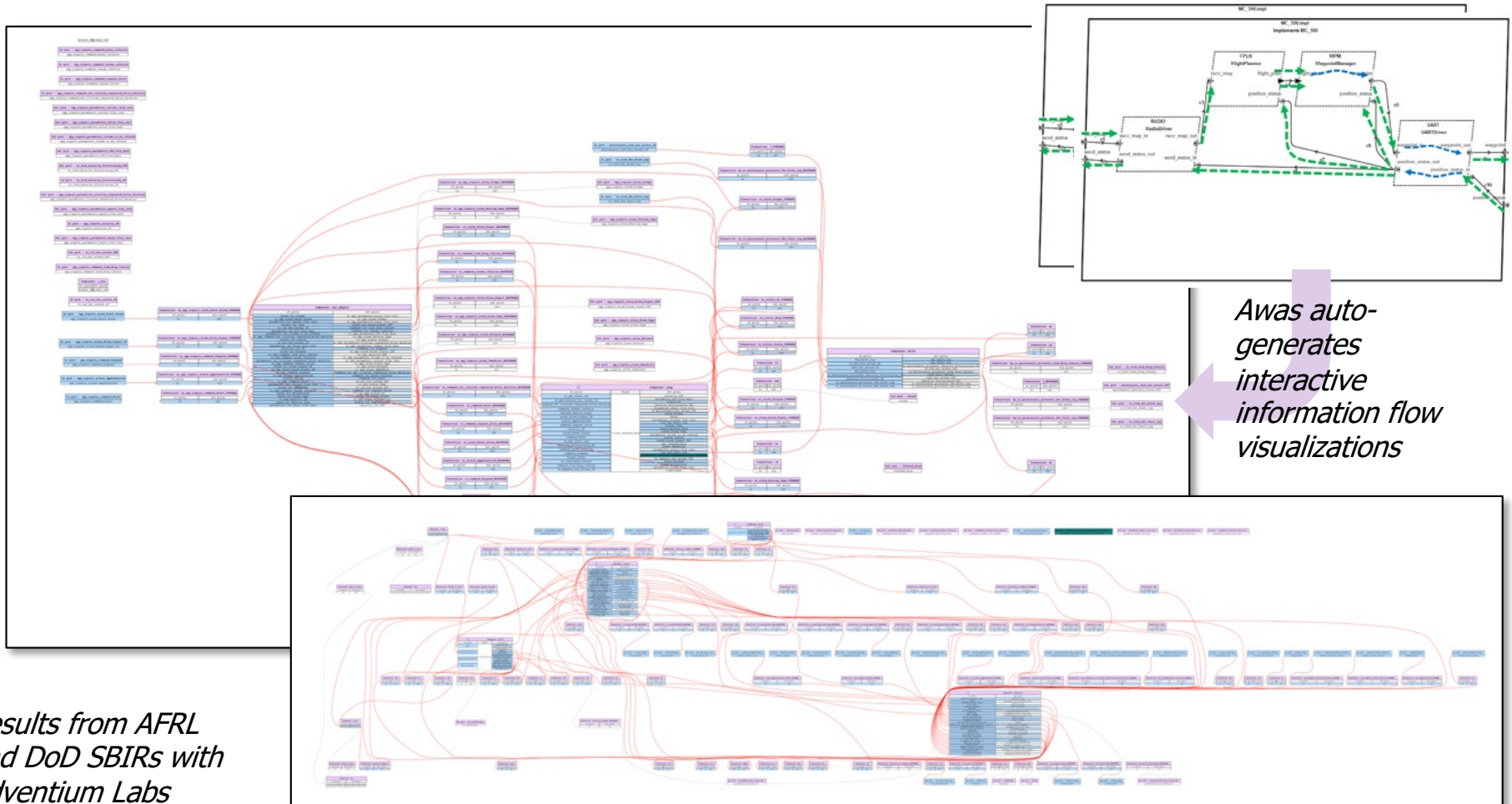


Contracts and Assume Guarantee Reasoning



AADL Analysis Example: Information Flow

The KSU Awas tool (<https://awas.sireum.org>) generates scalable interactive visualizations of AADL information flows and model-based hazard analysis results



Awas auto-generates interactive information flow visualizations

Results from AFRL and DoD SBIRs with Adventium Labs

Information flow graphs can be dynamically browsed and queried with path logic.

Intra-Component Information Flow

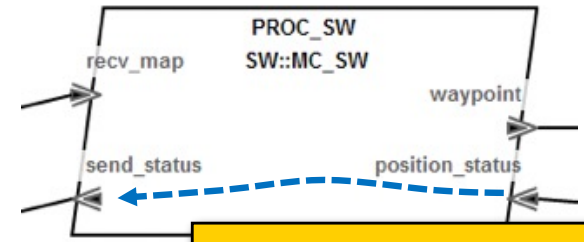
```
process MC_SW
```

```
features
```

```
  recv_map: in event data port Command.Impl;
  send_status: out event data port Coordinate.Impl;
  waypoint: out event data port MissionWindow.Impl;
  position_status: in event data port Coordinate.Impl;
```

```
flows
```

```
  compute_waypoint_flight_plan: flow path recv_map -> waypoint;
  compute_waypoint_pos_status :flow path position_status -> waypoint;
  compute_status : flow path position_status -> send_status;
```

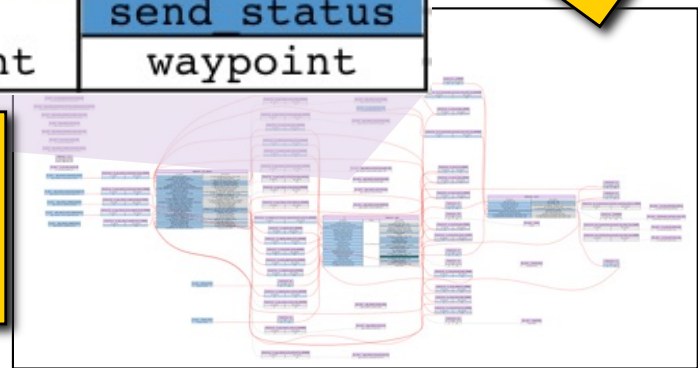


Specification of **flows** through **component application logic**

Example component node in visualization

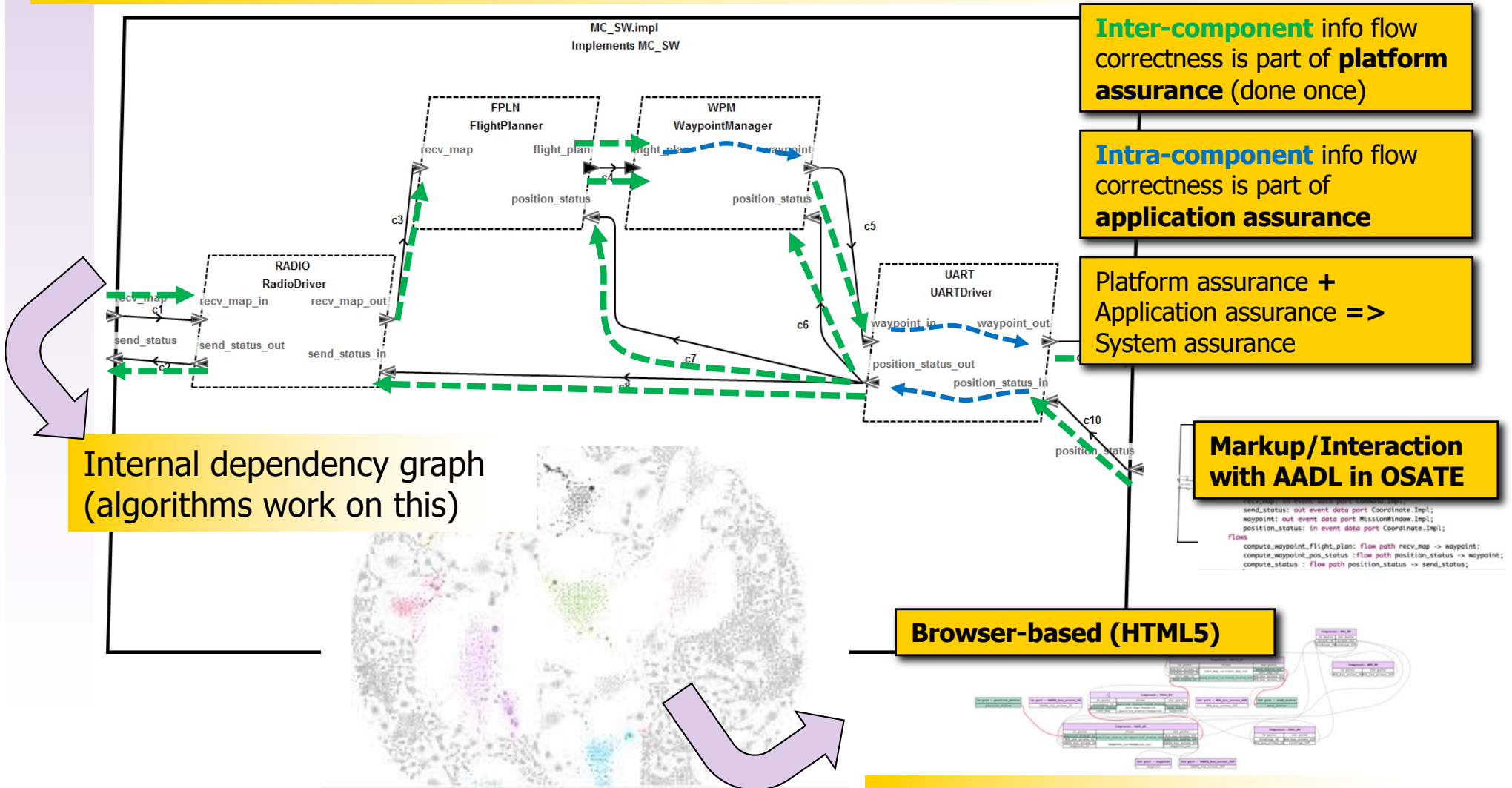
Component: PROC_SW		
In ports	Flows	Out ports
processor_IN	position_status->send_status	processor_OUT
position status	recv_map->waypoint	send status
recv_map	position_status->waypoint	waypoint

Awas component **visualizations focus developer attention on information flow aspects** (other aspects of AADL specs are elided)



Information Flow Analysis Foundation

Internal dependency graphs upon which analysis is performed are built from **architecture connections** and **intra-component AADL flow annotations** as well as AADL EM annotations



Inter-component info flow correctness is part of **platform assurance** (done once)

Intra-component info flow correctness is part of **application assurance**

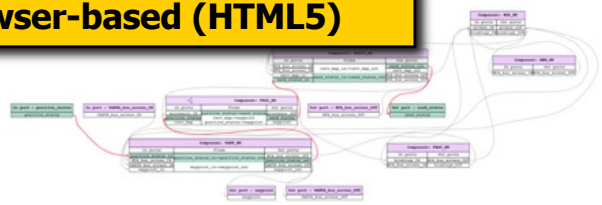
Platform assurance + Application assurance => System assurance

Internal dependency graph (algorithms work on this)

```

send_status: out event data port CoordinateImpl;
waypoint: out event data port MissionIndexImpl;
position_status: in event data port CoordinateImpl;
flows
compute_waypoint_flight_plan: flow path recv_map -> waypoint;
compute_waypoint_pos_status: flow path position_status -> waypoint;
compute_status: flow path position_status -> send_status;
    
```

Browser-based (HTML5)

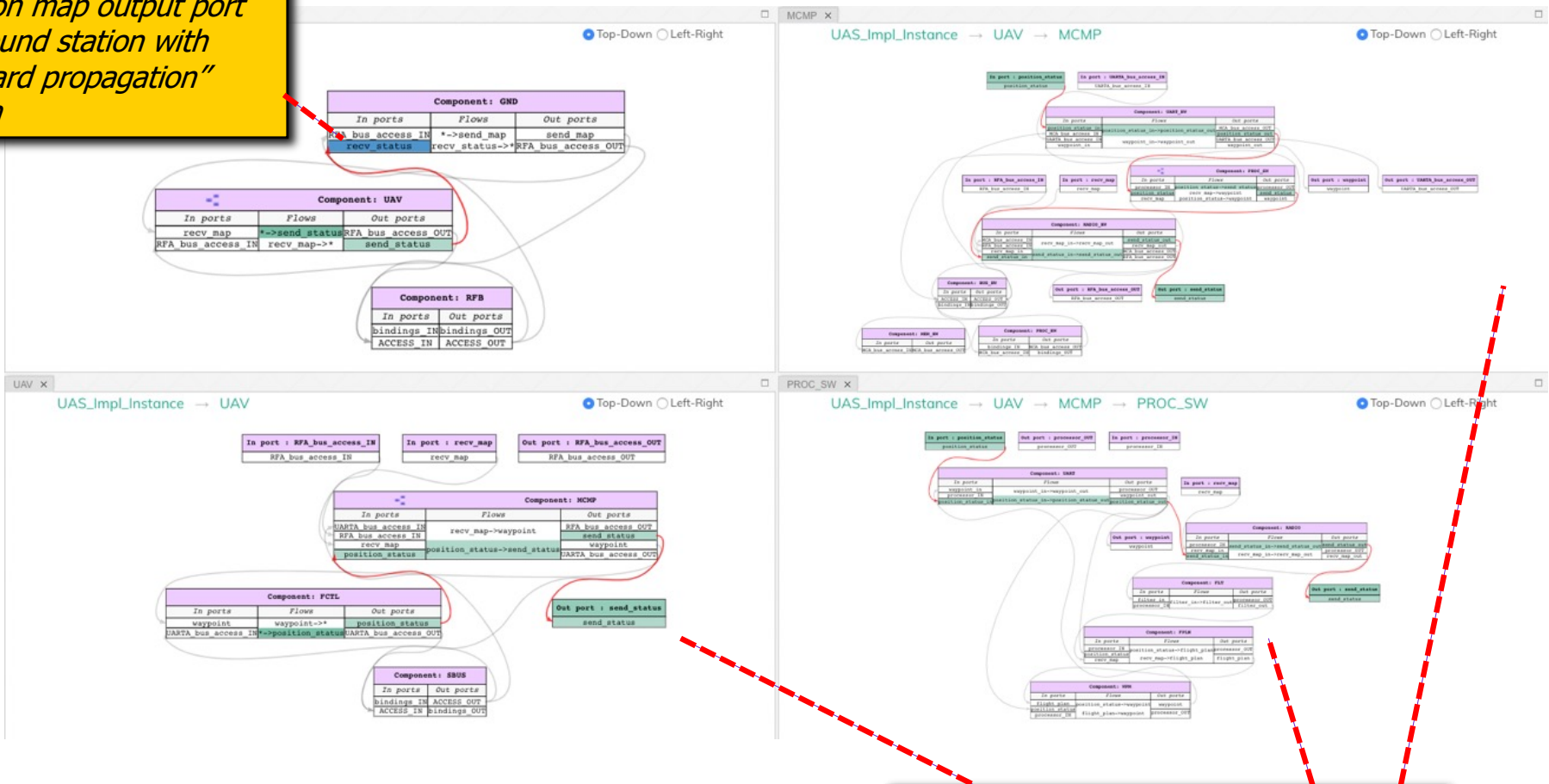


Interactions and rendered results

Interactive Browsing of Information Flows (AADL Level)

Example: In Ground Station / UAV example used on DARPA CASE, ask "how does map information propagation from ground station to UAV and through UAV's mission computer to produce a waypoint?"

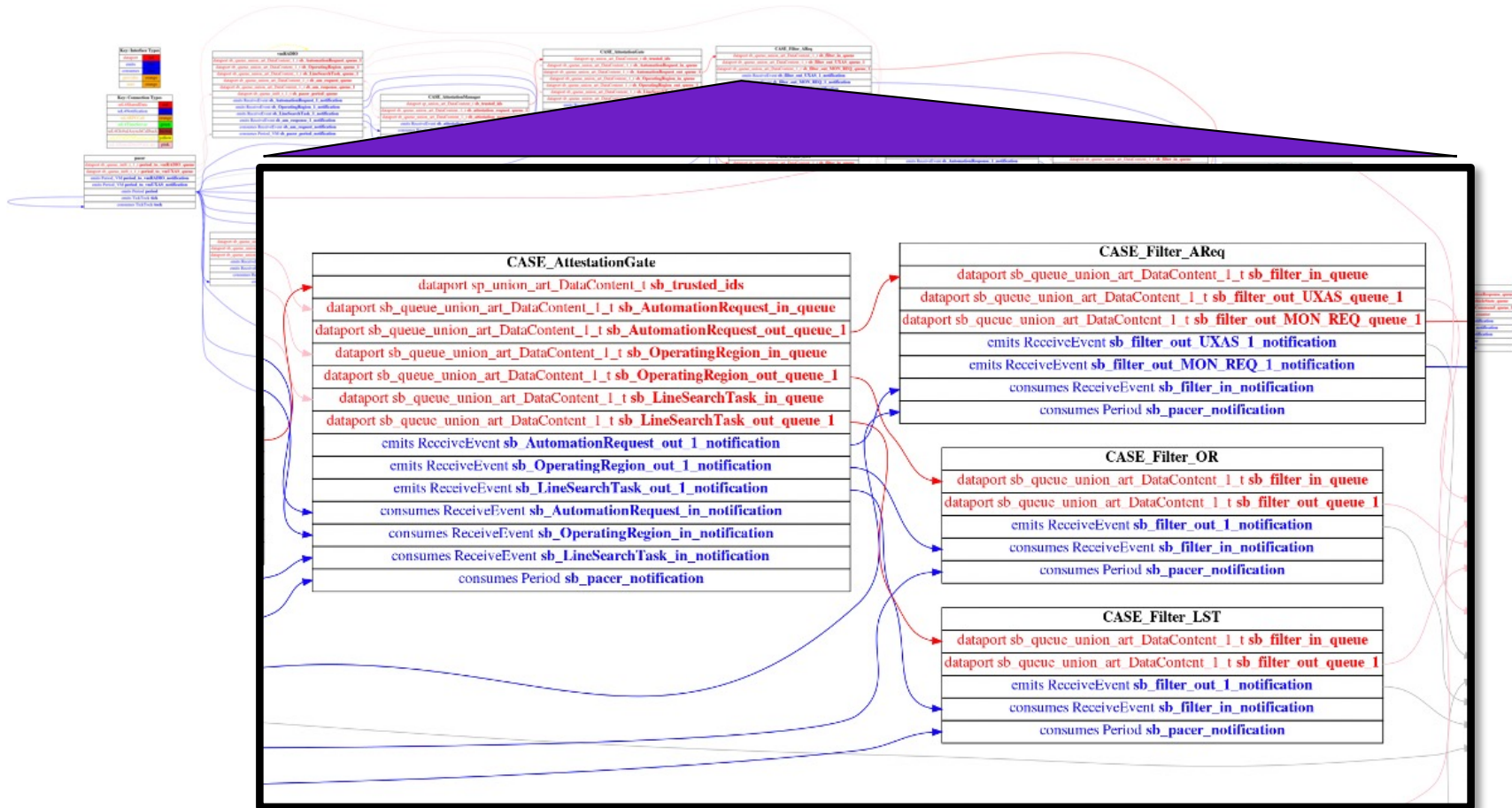
Click on map output port of ground station with "forward propagation" option



Immediately see results of across different subsystems.

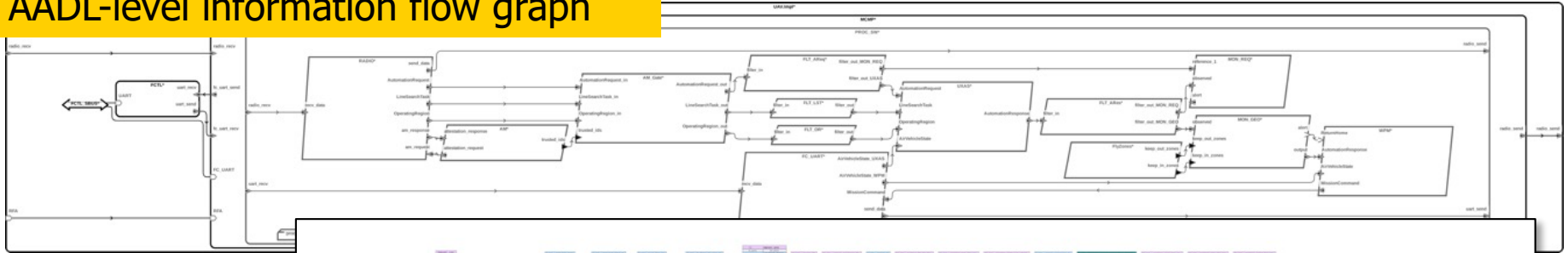
HAMR CAMkES/seL4 Platform Flows

HAMR generates graphs of CAMkES/seL4 platform flows (relying on assurance of CAMkES and seL4) along traceability information showing the correspondence between the model level specifications and realization of flow controls in the deployed code.

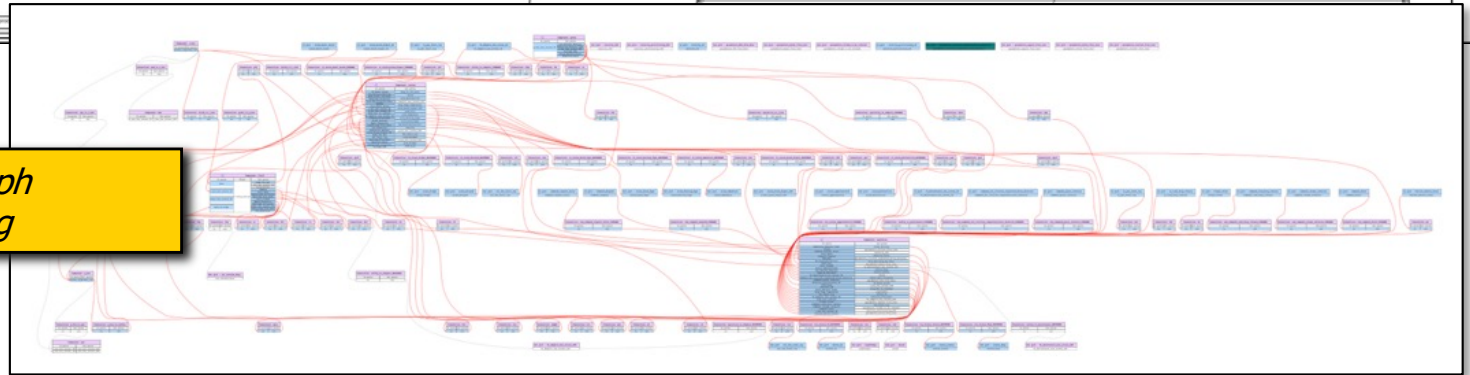


Platform Information Flow Assurance Sketch

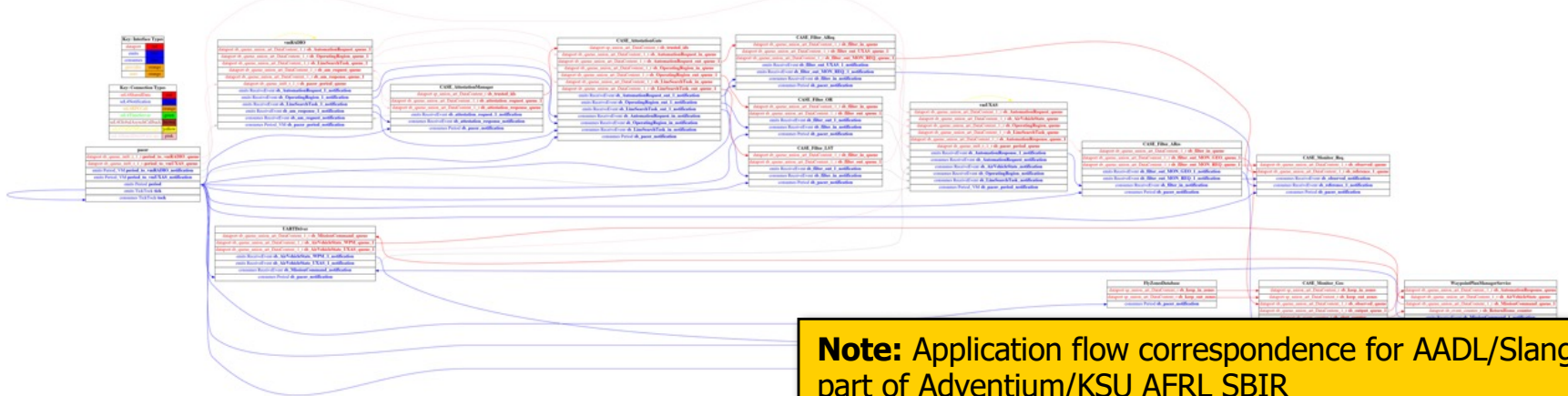
AADL-level information flow graph



SMT-based proof of graph isomorphism/embedding

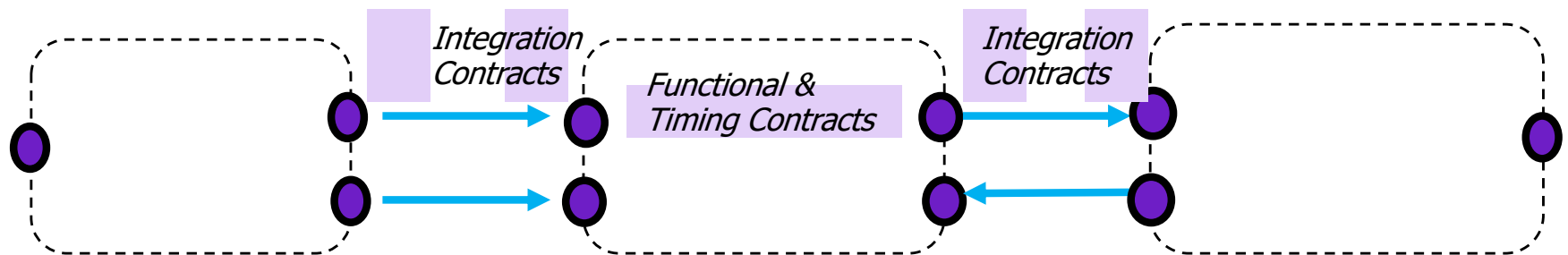


seL4 Platform-level information flow (at granularity of CAMkES topology)



Contracts for Compositional Reasoning

On-going work: supporting compositional verification in AADL and HAMR-generated applications...

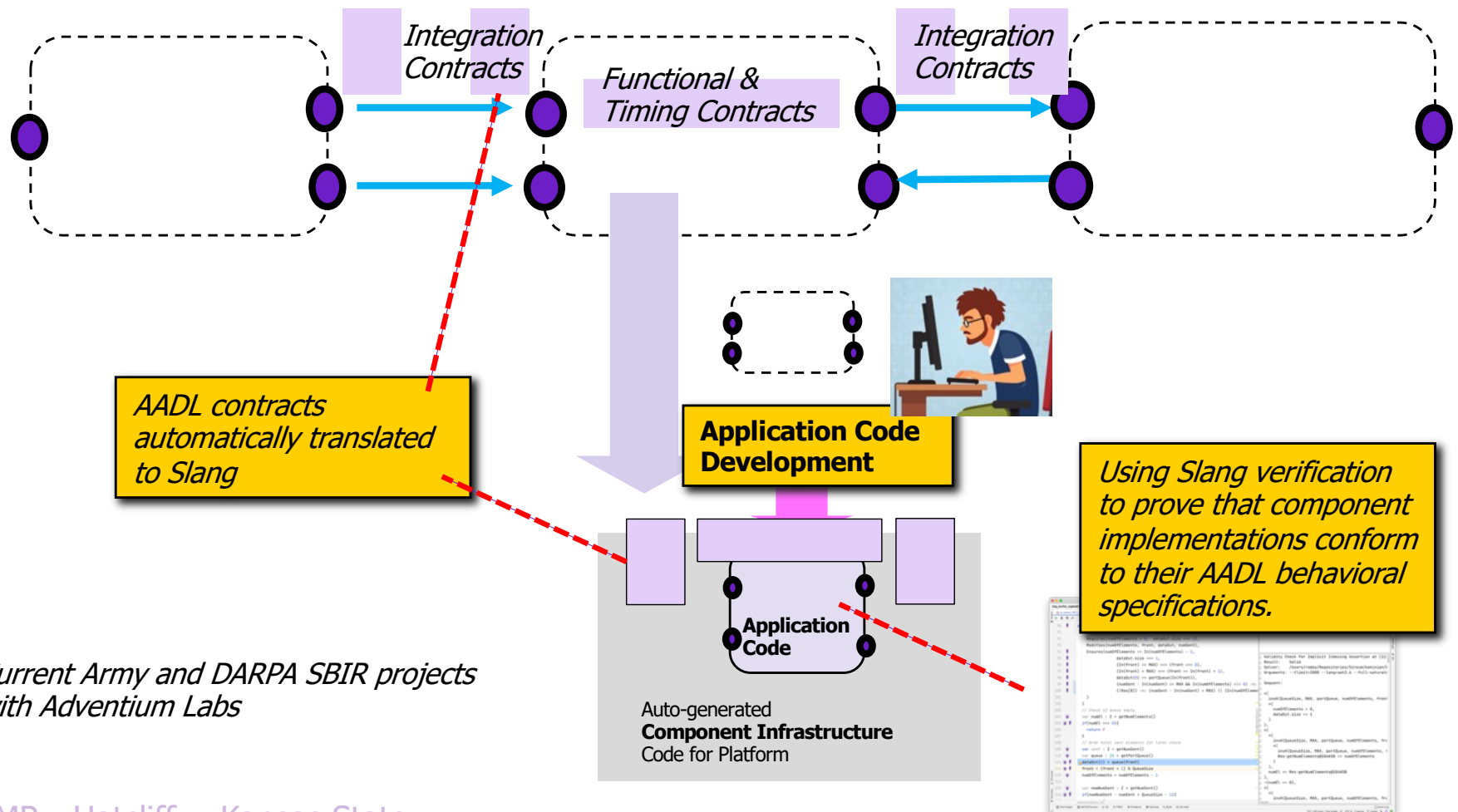


Existing AADL contract languages

- AGREE -- Assume-Guarantee REasoning Environment (used on DARPA CASE)
- BLESS – Behavior Language for Embedded Systems with Software

Contracts for Compositional Reasoning

On-going work: supporting compositional verification in AADL and HAMR-generated applications...



Current Army and DARPA SBIR projects with Adventium Labs

Slang Contracts and Automated Verification via Symbolic Execution

The screenshot shows an IDE window titled "ring_buffer - sp_queue_int8_t_dropOldest-sp-verified.sc [ring_buffer]". The code editor displays the following Slang code:

```

90 def dequeue(dataOut: ZS): B = {
91   Contract(
92     Requires(numOfElements > 0, dataOut.size == 1),
93     Modifies(numOfElements, front, dataOut, numSent),
94     Ensures(numOfElements == In(numOfElements) - 1,
95            dataOut.size == 1,
96            (In(front) == MAX) == (front == 0),
97            (In(front) < MAX) == (front == In(front) + 1),
98            dataOut(0) == portQueue(In(front)),
99            (numSent - In(numSent) <= MAX && In(numOfElements) != 0) ->:
100           (!Res[B] ->: (numSent - In(numSent) > MAX) || (In(numOfElements)
101           ))
102   )
103   // Check if queue empty
104   var numEl : Z = getNumElements()
105   if(numEl == 0){
106     return F
107   }
108   // Grab total sent elements for later check
109   var sent : Z = getNumSent()
110   var queue : ZS = getPortQueue()
111   dataOut(0) = queue(front)
112   front = (front + 1) % QueueSize
113   numOfElements = numOfElements - 1
114
115   var newNumSent : Z = getNumSent()
116   if(newNumSent - numSent > QueueSize - 1){

```

Annotations in the image:

- A red dashed box highlights the `Contract` block (lines 91-102), labeled "Slang Contract".
- A yellow box highlights the `dataOut(0) = queue(front)` line (line 111), labeled "Application Code".
- A red dashed circle highlights the `if` statement (lines 105-107), labeled "Verification Drill-down Controls".

The console window on the right shows the following output:

```

Validity Check for Implicit Indexing Assertion at [111, 22]: Valid
Validity Check for Implicit Indexing Assertion at [111, 11]: Valid

Validity Check for Implicit Indexing Assertion at [111, 11]: Valid
Result: Valid
Solver: /Users/robby/Repositories/Sireum/kekinian/t
Arguments: --tlimit=2000 --lang=smt2.6 --full-saturate

Sequent:
^ (
  invH(QueueSize, MAX, portQueue, numOfElements, front)
  ^ (
    ;
    numOfElements > 0,
    dataOut.size == 1
  )
),
^ (
  invH(QueueSize, MAX, portQueue, numOfElements, front)
  ^ (
    invH(QueueSize, MAX, portQueue, numOfElements, front)
    Res:getNumElements@104#38 == numOfElements
  )
),
numEl == Res:getNumElements@104#38
),
-(numEl == 0),
^ (
  invH(QueueSize, MAX, portQueue, numOfElements, front)

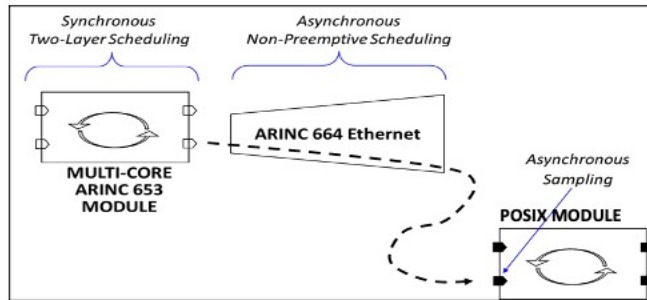
```

Slang applications can be integrated with Scala and Java and executed on JVM or translated to C (generated C is compatible with verified CompCert compiler)

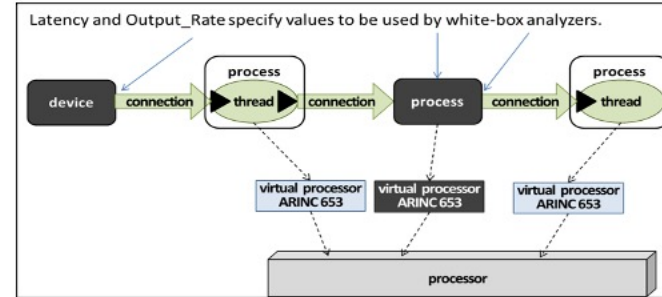
Automated Scheduling Analysis in AADL

Again, HAMR is leveraging the System Engineering emphasis of AADL – in particular, tools like Adventium’s FASTAR can process AADL model structure and timing annotations to perform schedulability analysis and automatically generate schedules.

Adventium® LABS FASTAR Schedule Generation 2020 seL4 Summit

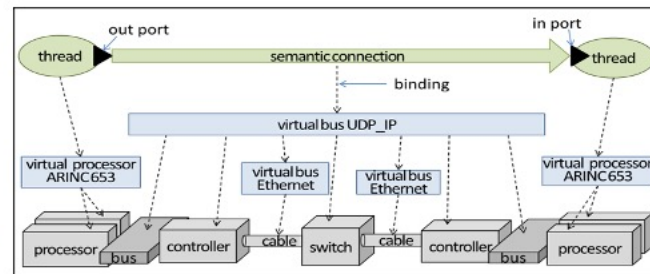


Heterogeneous Architectures



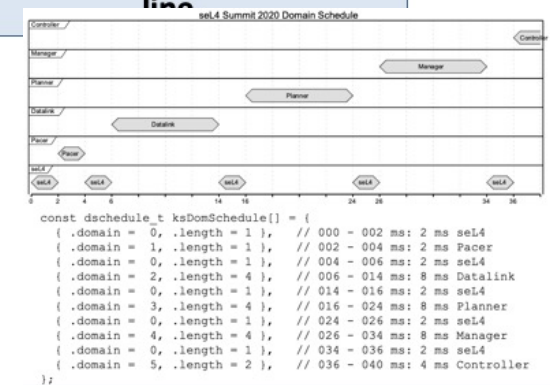
Mixed Fidelity Models

FASTAR analyzes resource needs and timing properties of complex architecture models as they evolve through multiple development phases.



Layered Architectures

FASTAR is itself a framework that integrates multiple other back-end tools selected to address the needs of a specific product line.



From Todd Carpenter's "Time Enough for seL4" talk in Assured Systems II session.

Related Work

HAMR enhances the HACMS Collins/U Minn/Data61 *Trusted Build* concept to provide...

- Completely new translation architecture with traceability mechanisms and support for eventual tool chain verification
- Alignment with AADL semantics
- Implementation of standardized AADL run-time services (key abstraction layer)
- Multiple platform support
- Multiple language support (adding Slang and CakeML)
- Automated insertion of virtual machines in seL4
- True one-way communication in seL4 (removing back channels)
- Traceability artifacts and information flow topology preservation proofs
- Temporal separation using seL4 domain scheduler



Sireum HAMR

High Assurance Model-based Rapid Engineering of
Embedded Systems

Other notable works on AADL code generation

- Ocarina – code generation for Ada and C (RT-POSIX threading, Xenomai, RTEMS, ARINC 653))
- RAMES – code generation for C (RT-Posix threading, nxtOSEK (LEGO Mindstorms), POK ARINC653-compliant).

Conclusion



Sireum HAMR

High Assurance Model-based Rapid Engineering of Embedded Systems

- HAMR helps support DARPA CASE goals by adopting multiple design goals that emphasis compositionality
- ... leading to a rich model-based systems engineering framework that supports multiple deployment platforms and multiple implementation languages
- ...emphasizing assurance and rigorous development practices

Resources on HAMR web site

- Distribution available for Windows, Linux, and Mac (also virtualized) hamr.sireum.org
- Documentation, examples, and tutorial material
- Educational resources -- slides, recorded lectures, and guided exercises for HAMR Slang back end

Questions



Sireum HAMR

High Assurance Model-based Rapid Engineering of
Embedded Systems

<http://hamr.sireum.org>