

# Verifying Hyperproperties with TLA

Fred B. Schneider

Samuel B Eckert Professor of Computer Science

Department of Computer Science  
Cornell University  
Ithaca, New York 14853  
U.S.A.

Joint work with Leslie Lamport

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# Overview

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- Hyperproperties
  - What and Why
- TLA
  - Important characteristics
- TLA verification of hyperproperties

# Hyperproperties

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behavior: an infinite sequence of states

$$\sigma = s_0 s_1 s_2 \dots s_i \dots$$

**Property**: A predicate on individual behaviors.

- Any sequential, concurrent, or distributed program (!)
- Partial correctness, total correctness
- Mutual exclusion
- Termination / Eventual service

**Hyperproperty**: A predicate on sets of behaviors.

- Information flow
- Memory consistency

# Verification of Hyperproperties?

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- Led to “new” methods being created.
  - Logic x + more stuff = Logic hyper-x
- But new methods are not necessary!
  - What attributes of an existing method are required?
  - Why.

# Properties and $\hat{P}$ predicates

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Property: set  $P$  of behaviors defined by predicates  $\hat{P}$  on behaviors  $\sigma$ :

$$\begin{aligned}\sigma \models \hat{P} &\stackrel{\text{def}}{=} \hat{P} \text{ is true on } \sigma \\ &= \sigma \in P\end{aligned}$$

Program: predicate  $\hat{S}$  on behaviors that defines a set  $S$  of behaviors

$$\begin{aligned}S \models \hat{P} &= S \subseteq P \\ &= (\forall \sigma: \sigma \in S \Rightarrow \sigma \in P) \\ &= (\forall \sigma: \sigma \models \hat{S} \Rightarrow \sigma \models \hat{P}) \\ &= (\forall \sigma: \sigma \models (\hat{S} \Rightarrow \hat{P})) \\ &= \models (\hat{S} \Rightarrow \hat{P})\end{aligned}$$

TLA is a logic where programs  $S$  are easily expressed as formulas  $\hat{S}$ .

# Universal Domains for States (rqmnt)

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" $\models (\hat{S} \Rightarrow \hat{P})$ " means "*true* in all interpretations  $\sigma$ "!  
 $\sigma: s_0 s_1 \dots s_i \dots$  What variables does  $s_i$  map?

Expect:

$$\frac{\models \hat{P}, \models \hat{Q}}{\models \hat{P} \wedge \hat{Q}}$$

Soundness then requires:

States in a behavior  $\sigma$  must map **all** variables to values.  
... including variables not in  $\hat{P}$  and not in  $\hat{Q}$

# Stuttering

(rqmnt)

Example: Clock specifications (seconds shouldn't matter)

$\widehat{HMS}$  behaviors are increasing: hrs  $h$ , mins  $m$ , secs  $s$ ;

$\widehat{HM}$  behaviors are increasing: hrs  $h$ , mins  $m$ .

$\models \widehat{HMS} \Rightarrow \widehat{HM} \quad ?$

$\langle 3:59:50 \rangle \dots \langle 3:59:59 \rangle \langle 4:00:00 \rangle \dots \models \widehat{HMS}$

$\langle 3:59 \rangle \langle 4:00 \rangle \dots \models \widehat{HM}$

$\langle 3:59:50 \rangle \dots \langle 3:59:59 \rangle \langle 4:00:00 \rangle \dots \not\models \widehat{HM}$

$\not\models \widehat{HMS} \Rightarrow \widehat{HM} !$

**Conclusion:** Predicates must be **stuttering insensitive** or else they constrain unnamed variables. *Specifications should constrain a system but not the whole universe!*

Toward verification of hyperproperties:

# Hyperproperties as Predicates

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A hyperproperty is defined by a predicate on properties  $P$ .

A **finitary hyperproperty**  $\mathcal{H}(P)$  is always equivalent to

$$\forall/\exists \sigma_1 \in P: \dots \forall/\exists \sigma_k \in P: \hat{J}(\sigma_1, \dots, \sigma_k)$$

where  $\hat{J}(\cdot)$  does not depend on  $P$ .



# Translate Sets to Predicates

1/2

$$\forall/\exists \sigma_1 \in P: \dots \forall/\exists \sigma_k \in P: \hat{J}(\sigma_1, \dots, \sigma_k)$$

**Translate:** Set membership to predicate satisfaction

- $\forall \sigma \in P: \dots$  into  $\forall \sigma: \hat{P}(\sigma) \Rightarrow \dots$
- $\exists \sigma \in P: \dots$  into  $\exists \sigma: \hat{P}(\sigma) \wedge \dots$

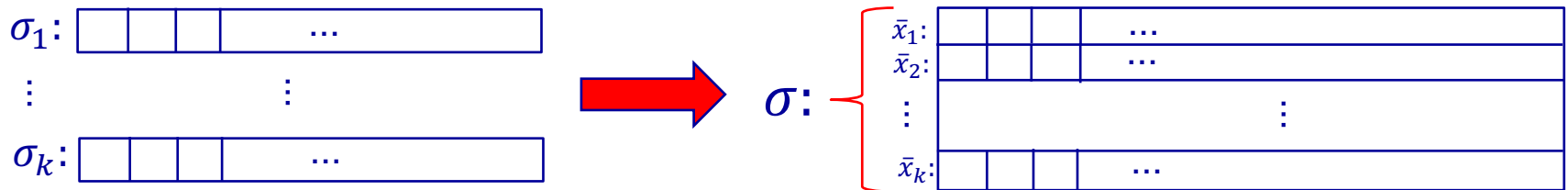
# Translate Sets to Predicates

2/2

**Translate:** Predicates on behaviors to Temporal Logic formulas on variables

-  $\hat{J}(\dots, \sigma_i, \dots)$  into  $\hat{J}(\dots, \bar{x}_i, \dots)$

where  $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_k$  are disjoint lists. [*Cf Self-Composition*]



Temporal Logic inference or model checking does the rest.

*We have: Reduced hyperproperty verif to property verif!*

# $\forall\exists$ -Hyperproperties in TLA

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A subclass of finitary hyperproperties:

$$\begin{aligned} & \hat{P}(\bar{x}_1) \wedge \cdots \wedge \hat{P}(\bar{x}_j) \wedge \hat{K}(\bar{x}_1, \dots, \bar{x}_j) \\ & \Rightarrow (\exists \bar{x}_{j+1} \dots, \bar{x}_k: \hat{P}(\bar{x}_{j+1}) \wedge \cdots \wedge \hat{P}(\bar{x}_k) \\ & \quad \wedge \hat{L}(\bar{x}_1, \dots, \bar{x}_k)) \end{aligned}$$

- A class of formulas TLA<sup>+</sup> model checker handles.
- Class is expressive enough to handle all hyperproperties we have encountered in literature.

# Why SI: GNI case study 1/4

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**Generalized Non-interference (GNI):** For any behaviors  $\sigma_1$  and  $\sigma_2$  in  $P$ , there is a behavior  $\sigma_3$  exhibiting the public events of  $\sigma_1$  and the secret events of  $\sigma_2$ .

$$\hat{P}(\bar{x}_1) \wedge \hat{P}(\bar{x}_2) \Rightarrow (\exists \bar{x}_3: \hat{P}(\bar{x}_3) \wedge \hat{L}(\bar{x}_1, \bar{x}_2, \bar{x}_3))$$

$$\hat{L}(\bar{x}_1, \bar{x}_2, \bar{x}_3) \stackrel{\text{def}}{=} \square(\text{pub}(\bar{x}_3) = \text{pub}(\bar{x}_1) \wedge \text{sec}(\bar{x}_3) = \text{sec}(\bar{x}_2))$$

# Why SI: GNI case study 2/4

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$$\hat{P}(\bar{x}_1) \wedge \hat{P}(\bar{x}_2) \Rightarrow (\exists \bar{x}_3: \hat{P}(\bar{x}_3) \wedge \hat{L}(\bar{x}_1, \bar{x}_2, \bar{x}_3))$$

$$\hat{L}(\bar{x}_1, \bar{x}_2, \bar{x}_3) \stackrel{\text{def}}{=} \square(\text{pub}(\bar{x}_3) = \text{pub}(\bar{x}_1) \wedge \text{sec}(\bar{x}_3) = \text{sec}(\bar{x}_2))$$

Example:  $\hat{P}(\bar{x}_1)$ : steps  $ps(\bar{x}_1)$  alternates with  $ss(\bar{x}_1)$ , where:

- $ps(\bar{x}_1)$  step updates  $\text{pub}(\bar{x}_1)$  but not  $\text{sec}(\bar{x}_1)$
- $ss(\bar{x}_1)$  step updates  $\text{sec}(\bar{x}_1)$  but not  $\text{pub}(\bar{x}_1)$

# Why SI: GNI case study 3/4

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$$\hat{P}(\bar{x}_1) \wedge \hat{P}(\bar{x}_2) \Rightarrow (\exists \bar{x}_3: \hat{P}(\bar{x}_3) \wedge \hat{L}(\bar{x}_1, \bar{x}_2, \bar{x}_3))$$

$$LL(\bar{x}_1, \bar{x}_2, \bar{x}_3) \stackrel{\text{def}}{=} \square(\text{pub}(\bar{x}_3) = \text{pub}(\bar{x}_1) \wedge \text{sec}(\bar{x}_3) = \text{sec}(\bar{x}_2))$$

$\bar{x}_1$ :  $s_1$   $ps(\bar{x}_1)$   $s_2$   $ss(\bar{x}_1)$   $s_3$   $ps(\bar{x}_1)$   $s_4$  ...

$\bar{x}_2$ :  $t_1$   $ps(\bar{x}_2)$   $t_2$   $t_3$   $ss(\bar{x}_2)$   $t_4$  ...

$\bar{x}_3$ :  $u_1$   $ps(\bar{x}_3)$   $u_2$   $u_3$  ???  $u_4$  ...

# Stuttering Insensitivity (SI)

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Behaviors  $\sigma$  and  $\tau$  are **stuttering equivalent** if deleting repeated values from each produces identical sequences.

- Define  $\sigma \models (f \sim g)$  iff  $\sigma|_f$  and  $\sigma|_g$  are stuttering equivalent, where **projection**  $\sigma|_f$  is sequence of values  $\sigma$  gives to state function  $f$ .

TLA is a linear-time temporal logic where all formulas are SI.

- $\hat{S} \Rightarrow \hat{P}$  can mean  $\hat{S}$  satisfies/implements  $\hat{P}$
- Can “form” a behavior for execution that combines executions described by behaviors  $\sigma_1$  and  $\sigma_2$  (needed for some hyperproperties).

# Why SI: GNI case study 4/4

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$$\hat{P}(\bar{x}_1) \wedge \hat{P}(\bar{x}_2) \Rightarrow$$

$$(\exists \bar{x}_3, \bar{y}_1, \bar{y}_2: \bar{y}_1 \sim \bar{x}_1 \wedge \bar{y}_2 \sim \bar{x}_2 \wedge \hat{P}(\bar{x}_3) \\ \wedge \hat{L}(\bar{y}_1, \bar{y}_2, \bar{x}_3))$$

$$LL(\bar{x}_1, \bar{x}_2, \bar{x}_3) \stackrel{\text{def}}{=} \square(\text{pub}(\bar{x}_3) = \text{pub}(\bar{x}_1) \wedge \text{sec}(\bar{x}_3) = \text{sec}(\bar{x}_2))$$

- $\bar{y}_1 \sim \bar{x}_1, \bar{y}_2 \sim \bar{x}_2$  accounts for SI behaviors in  $\hat{P}(\cdot)$ .



# $\forall\exists$ -Hyperproperties Examples

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- **Generalized Non-interference:** For any behaviors  $\sigma_1$  and  $\sigma_2$  in  $P$ , there is a behavior  $\sigma_3$  exhibiting the public events of  $\sigma_1$  and the secret events of  $\sigma_2$ .
- **Observational non-determinism.** Two system behaviors with same initial public state are public-stuttering equivalent.
- **Non-interference.** Deleting secret commands has no effect on public outputs.
- **Possibilistic non-interference.** If  $\sigma_1$  and  $\sigma_2$  have the same initial public values *then* there exists a behavior  $\sigma_3$  with the same initial state as  $\sigma_2$  and the same public values as  $\sigma_1$  throughout.

# Summary

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- Hyperproperties provide needed expressiveness for security and concurrency.
- Existing logics + self composition works if:
  - States map all variables.
    - Already needed for ordinary compositionality
  - Behaviors are stuttering insensitive.
    - Already needed for “implements” to be implication ( $\Rightarrow$ )
- TLA+ is such a logic, used in industry and with a model checker for support.

# Reading

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- M. Clarkson and F.B. Schneider. Hyperproperties. *Journal of Computer Security* 18 (2010).
- L. Lamport. The temporal logic of actions. *ACM Transactions on Programming Languages and Systems*, 16(3), May 1994, 872--923.
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