

Assurance-Case Driven Framework to Support Cyber-Physical Systems

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- Safety critical applications have been almost everywhere



- Failure of safety critical systems have some serious consequences. Software becomes a main reason for failure of these systems.

More than a quarter (25.7%) of all medical device recalls in Q4 2017 were due to software issues, making it the top cause for the seventh consecutive quarter

- Software assurance becomes an important issue when certifying a CPS

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- Most current system certifications are done manually.

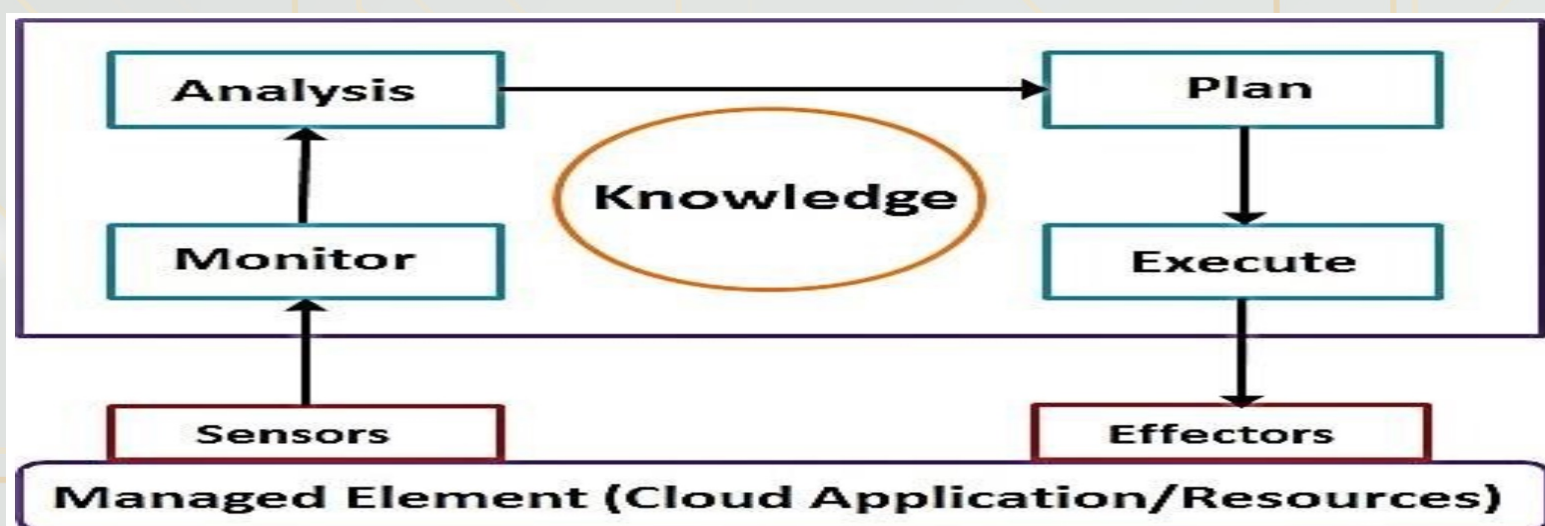


- Assurance case has become a main mechanism among different stakeholders to ensure that a CPS can be relied upon.

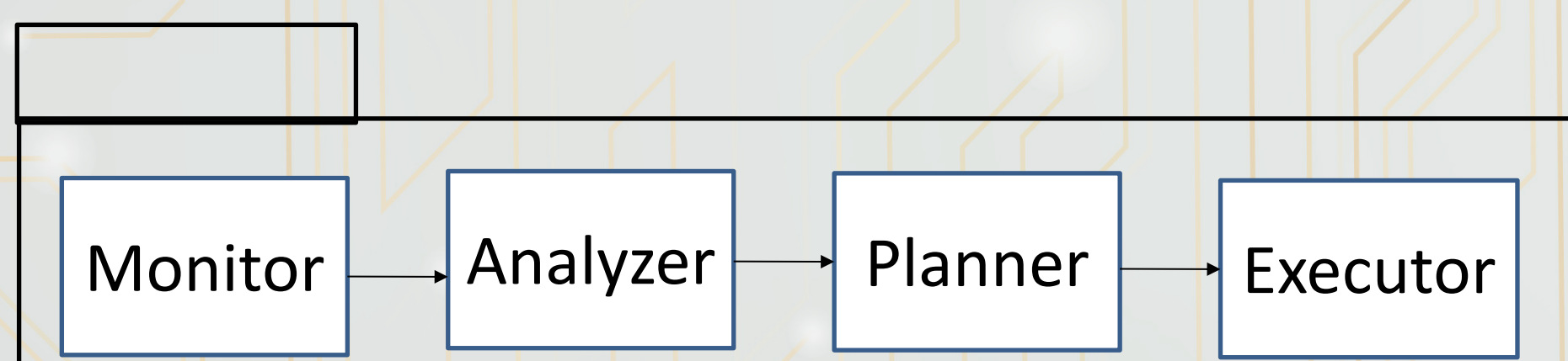
- To reduce the burden of developers and certifiers, we propose a new framework that employs the assurance case as a driving force during the design and runtime

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- The MAPE-K process widely used in a CPS



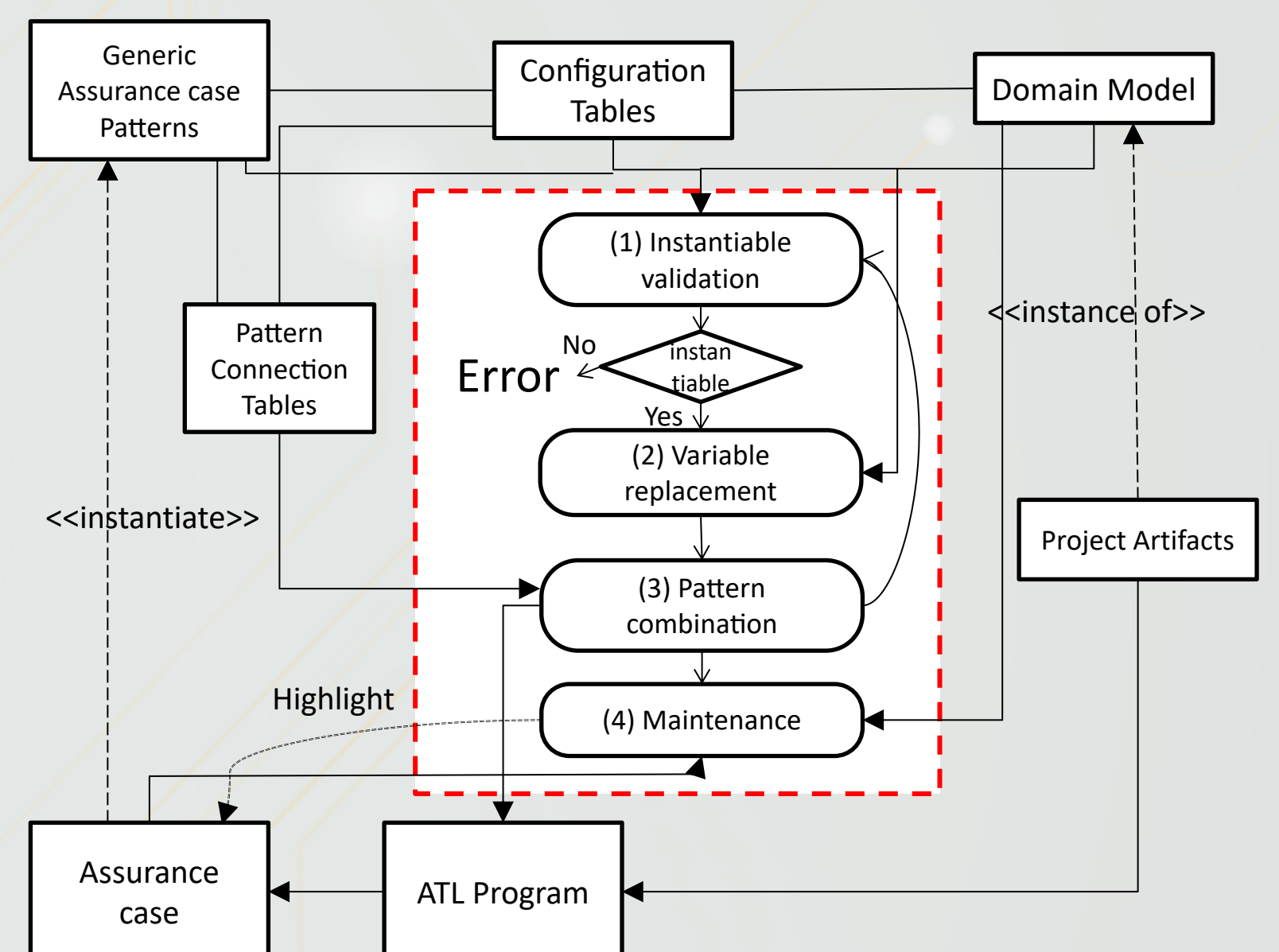
- Software Design for the MAPE-K



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- Assurance Case Driven Framework

– Design time



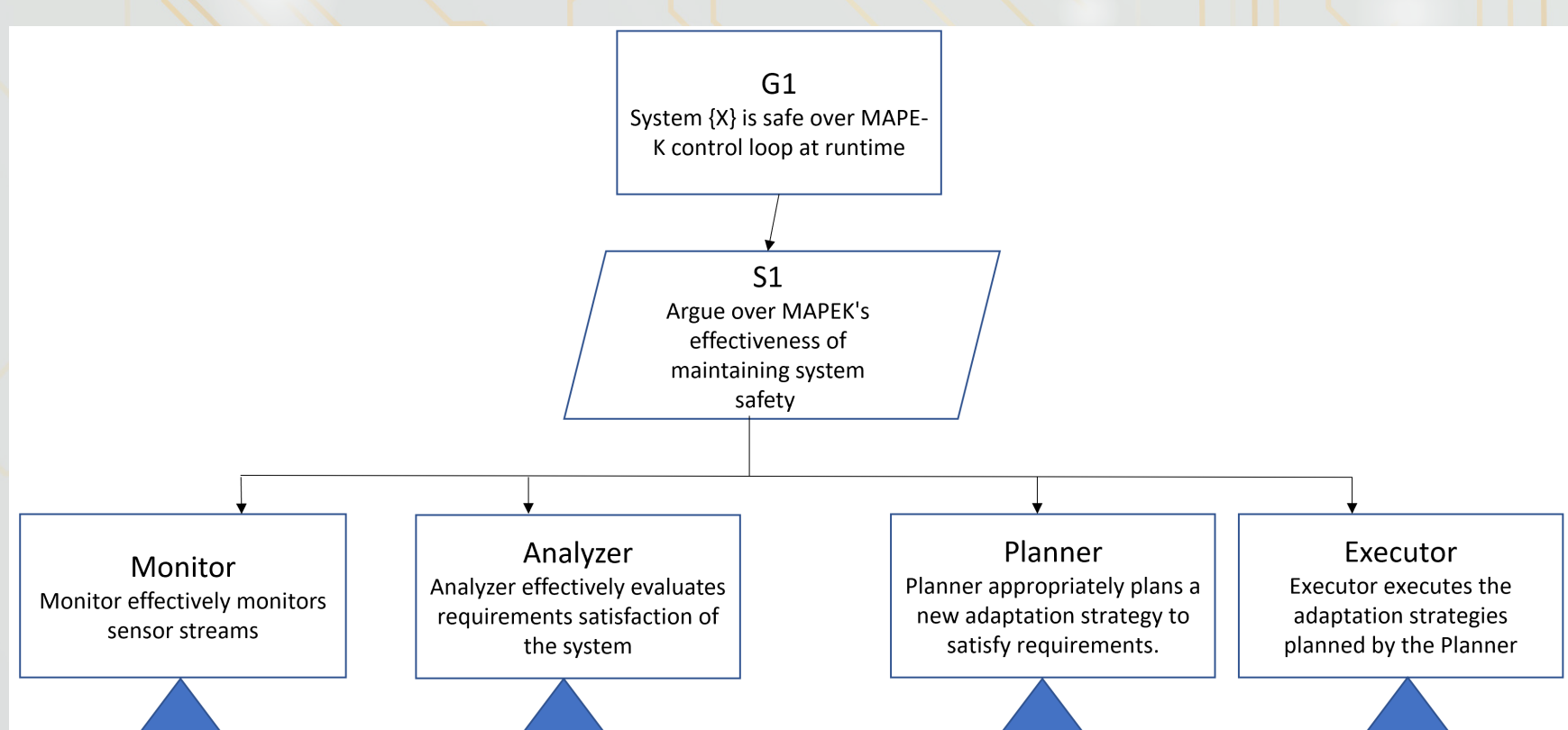
– Design Time Certification: D-S Theory

- D-S theory is a general framework for reasoning with uncertainty.
- For each claim A, the frame of discernment is denoted as $\Omega_A = \{A, \bar{A}\}$
- The mass function $m^\Omega(P) \in [0,1]$ denotes the degree of belief committed to the hypothesis that the truth lies in P where P is a power set of Ω , i.e. $P \in 2^\Omega$

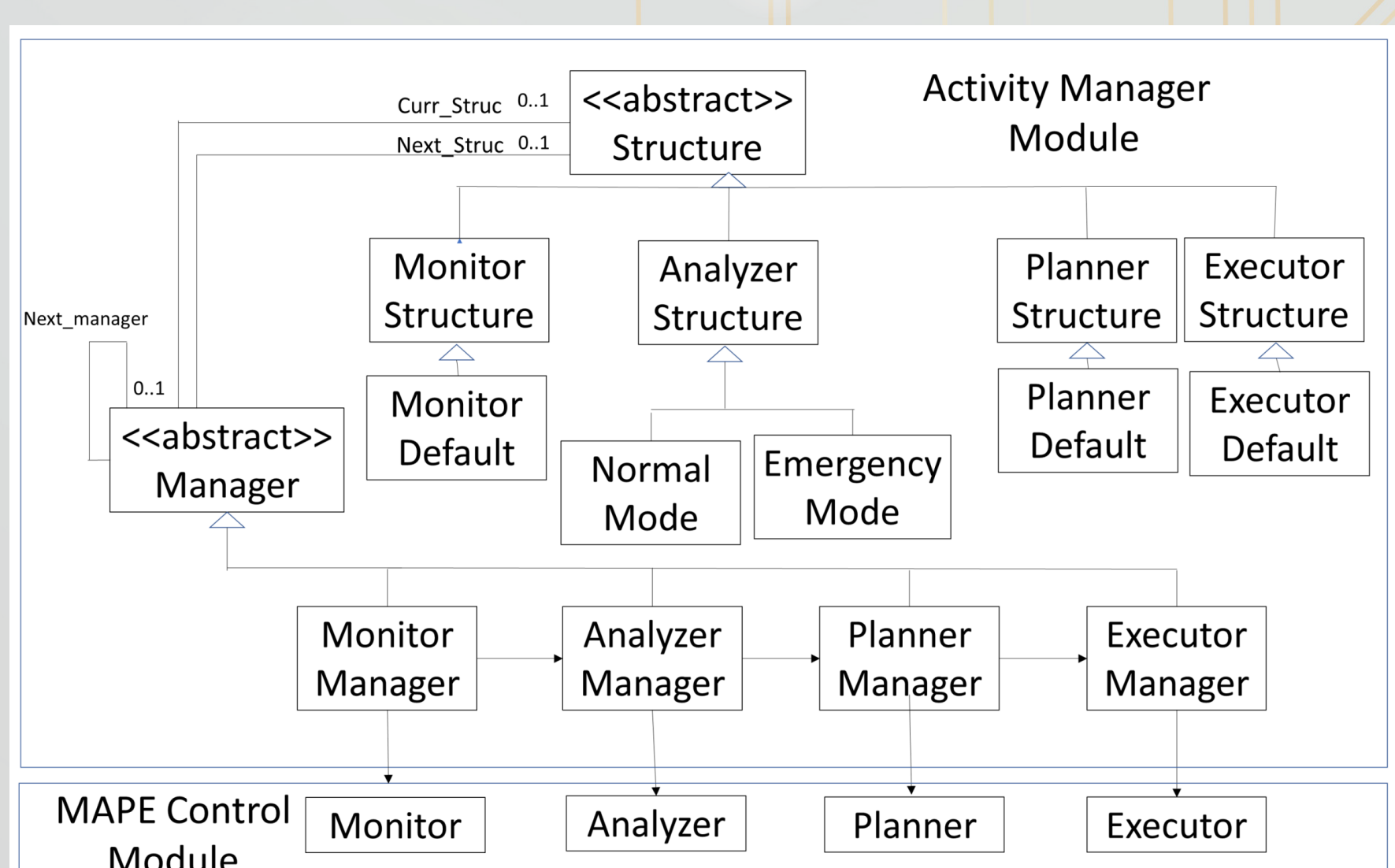
$$\begin{cases} bel_A = m(A) & \text{represents the belief in } A \\ disb_A = m(\bar{A}) & \text{represents the disbelief of } A \\ uncer_A = 1 - bel_A - disb_A & \text{represents the uncertainty} \end{cases}$$

- Assurance Case Driven Framework @Runtime

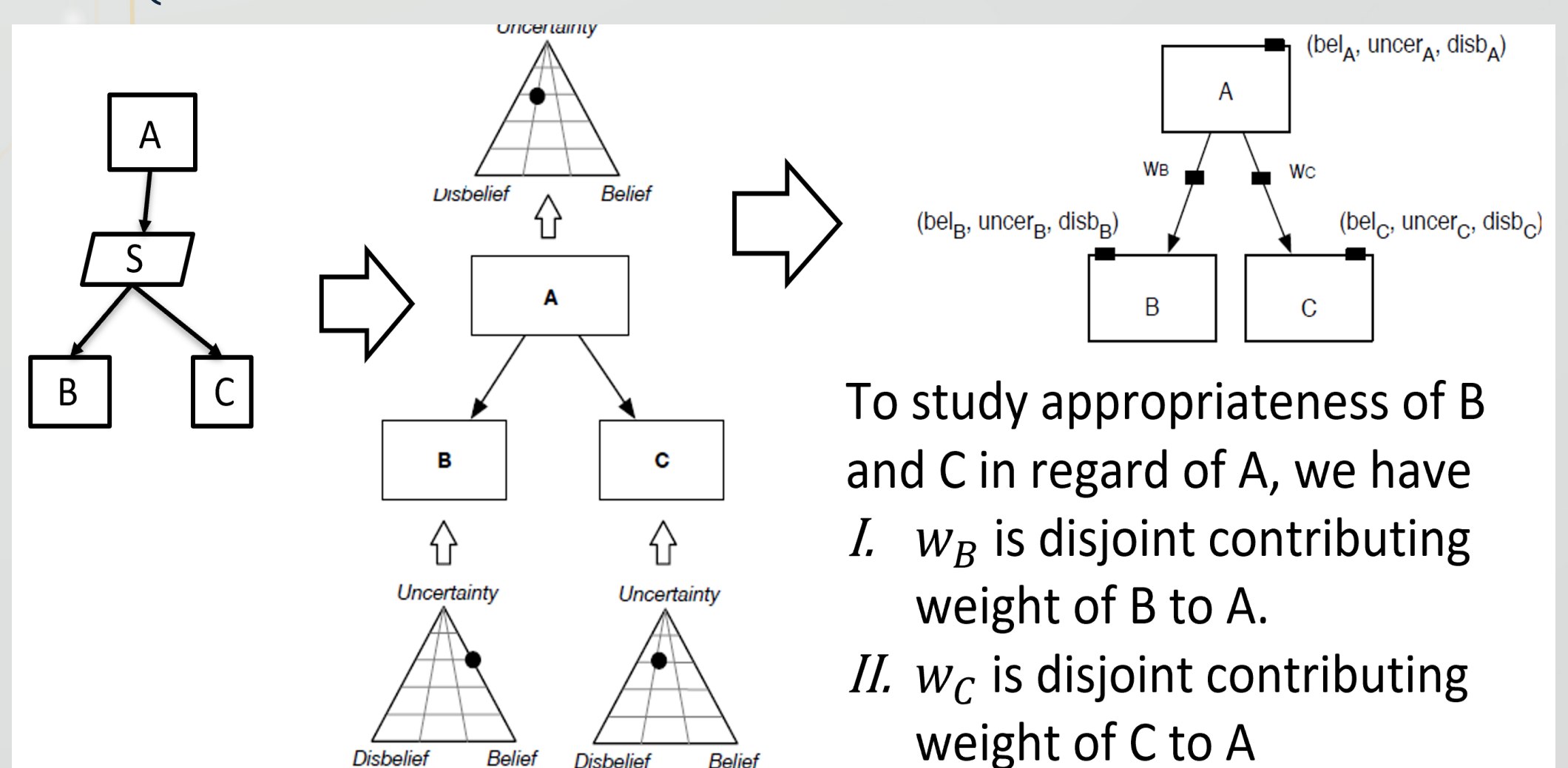
– Assurance Case Template



– Design of the Framework to Support runtime adaptive feature



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- To study appropriateness of B and C in regard of A, we have
- I. w_B is disjoint contributing weight of B to A.
 - II. w_C is disjoint contributing weight of C to A
 - III. v is called discounting factor

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